



**ICUS** 2022 IEEE International Conference on Unmanned Systems

**Best Paper Award**

presented to

**Liuchao Jin, Yuchen Lou, Lu-An Chen, and Qi Lu**

for the paper entitled

The Unified Tracking Controller for a Tilt-Rotor Unmanned Aerial Vehicle Based on the Dual Quaternion

October 28 - 30, 2022 Guangzhou, China

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