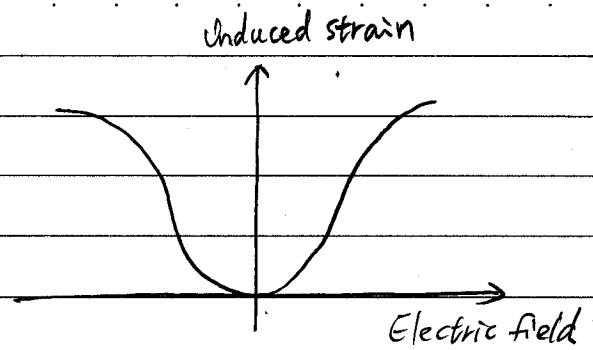


## Electrostrictive Materials:

- similar to piezoelectric materials with slightly higher free strain
- nonlinear strain-field relations
- very sensitive to temperature



## Magnetostrictive Materials: (e.g. Terfenol-D)

- produce strains when exposed to magnetic field
- highly nonlinear between applied magnetic field and induced strains
- magnetostrictive transducers are large in size
- far from fragile once housed and prestressed

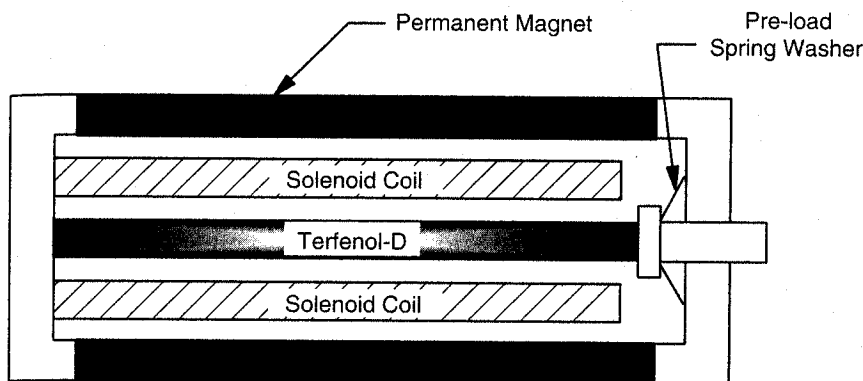
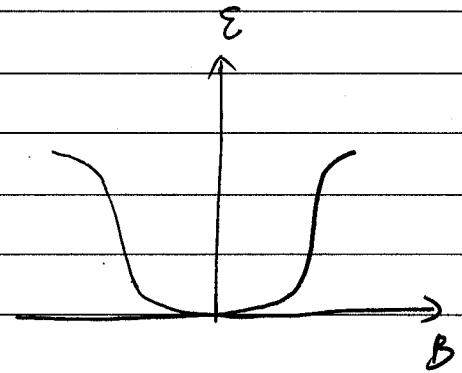
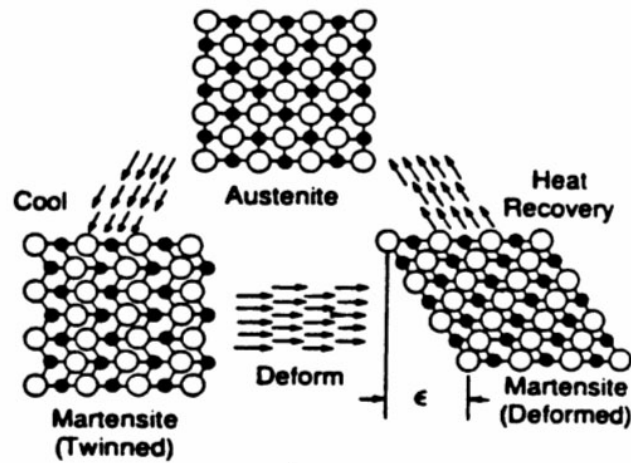


Figure 5.3: Schematic diagram of a Terfenol-D actuator.

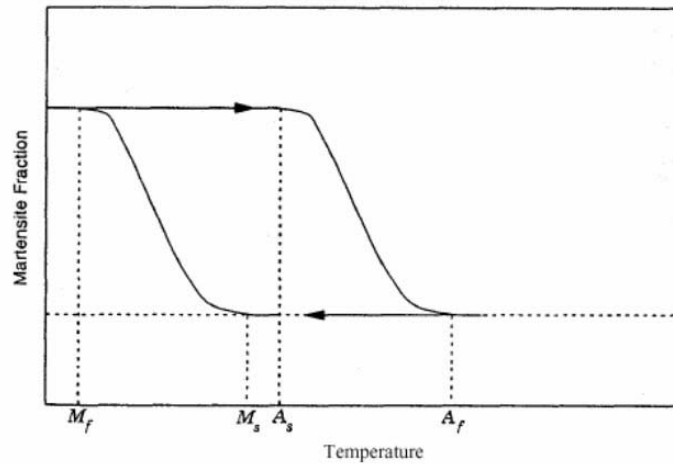
## Shape Memory Alloys (SMAs)

- capable of memorizing its original configuration after heated above the characteristic transition temperature
- can produce large displacements and forces
- most common SMA is Nitinol  
Ni: nickel, Ti: titanium  
nol: Naval Ordnance Laboratory
- heat may be internal (electrical heating)
- slow response time
- nonlinear hysteresis
- modeling is quite difficult

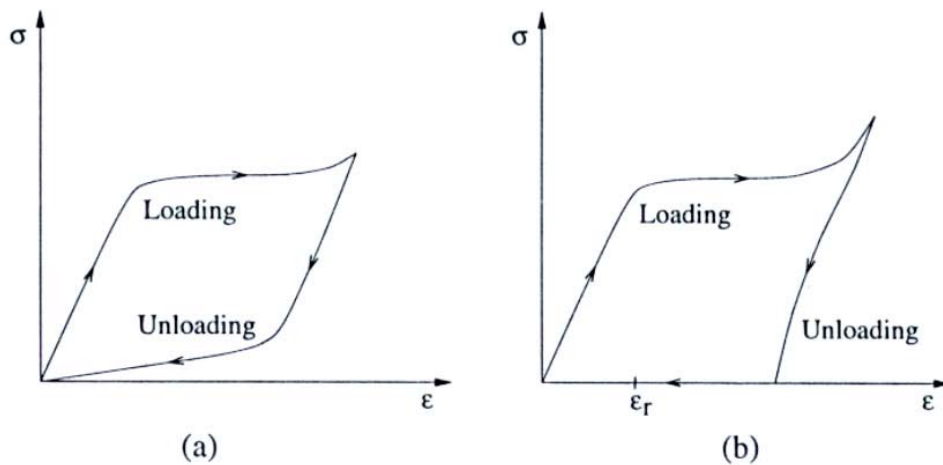
- Pseudoelastic: when an SMA is in the austenite phase ( $T > A_f$ ), a plastic strain is achieved under stress loading, the full strain can be recovered upon unloading.
- Shape memory effect: when  $T < A_s$  during the stress-induced martensite phase transformation, a large residual strain  $\epsilon_r$  remains after unloading. This strain can be recovered by heating SMA to  $T > A_f$ .



Representation of the changes in the crystal form of SMAs which leads to the shape memory effect



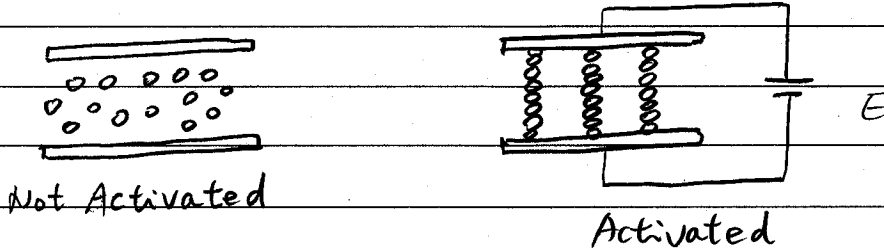
Schematic diagram of transformation of a shape memory alloy



(a) Pseudoelasticity: stress-strain hysteresis loop ( $T > A_f$ )  
 (b) Shape memory effect: residual strain  $\epsilon_r$  ( $T < A_s$ )

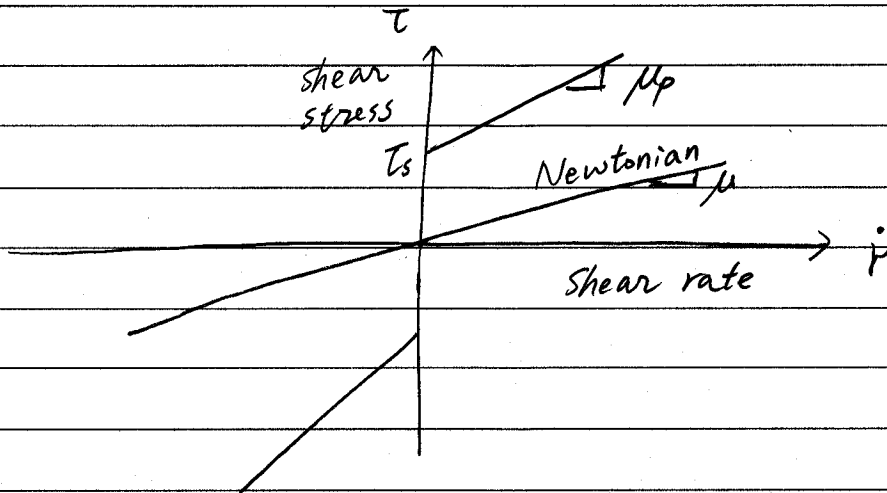
## Electro-rheological (ER) Fluids

- ER fluids are colloidal dispersions of solid particulates in nonconducting or insulating oils
- display reversible changes in dynamic yield stress due to an application of an electric field



- A recipe for a couple of ER fluid

1 cup of mineral oil + 1 cup of starch = 2 cups of ER fluid



Newtonian fluid  $\tau = \mu \dot{\gamma}$   
where  $\mu$  is the absolute viscosity

Bingham plastic  $\tau = \tau_s + \mu_p \dot{\gamma}$

## • Disadvantages (ER Fluids):

- high voltage required
- lack of long term stability
- complexity of actuator / control design

## Magneto-rheological (MR) Fluids

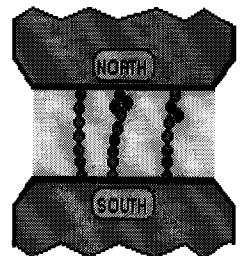
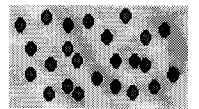
- suspensions of micro-sized, magnetizable particles in oil.  
e.g. soft iron particles in mineral oil
- Newtonian in absence of applied field
- develop yield strength when field applied  
high yield stress = 50-100 kPa for  
150-250 kA/m ( $\approx 2-3$  kG)  
cf. ER Fluid = 2-5 kPa for 3-5 kV/mm
- Bingham plastic model:

$$\tau = \tau_s(H) + \mu_p \dot{\gamma}$$

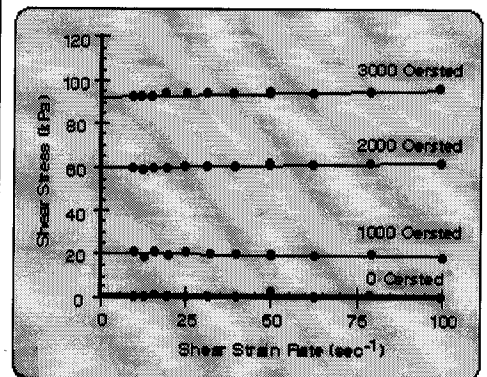
- Good stability

- Fast response time

- Broad operating temperature range



Shear Flow Behavior of Typical MR Fluid

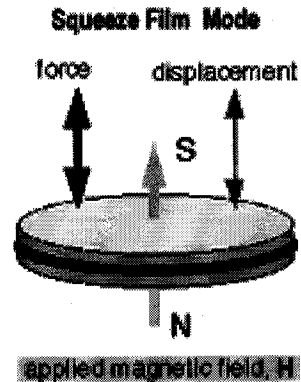
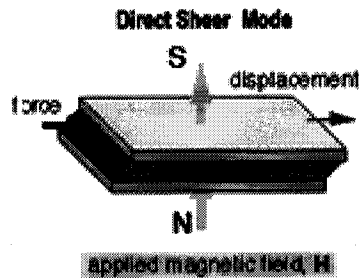
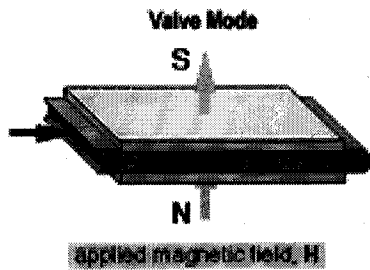


• Three basic modes of operation for MR Fluids:

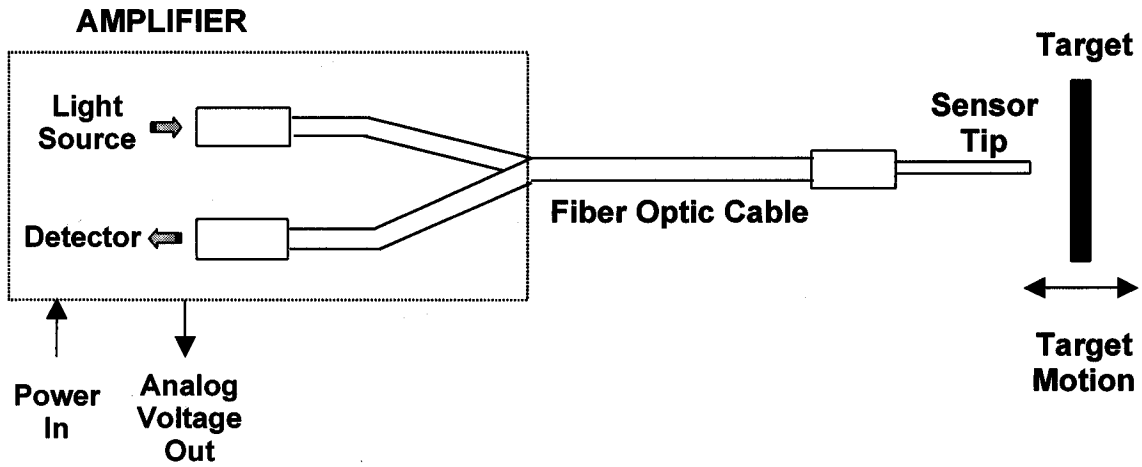
(a) flow mode (valve mode)

(b) shear mode (clutch mode)

(c) squeeze mode (compression mode)



# Fiber Optic Sensors



- lightweight
- mechanically flexible, diverse geometry possible
- low maintenance, high reliability
- no actuation abilities