

# Computational Mechanics

## Chapter 11 Constitutive Models – Plasticity

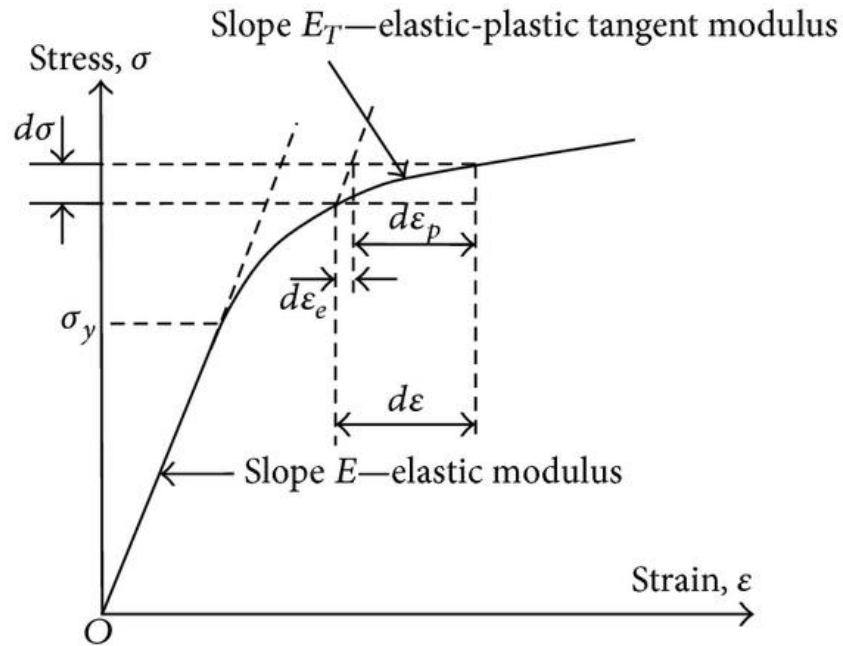


# Characteristic of Plasticity

- Plasticity: **permanent** strains are developed upon **unloading**
- Yield strength: stress when plastic strains are developed
- Major ingredients of plasticity theory:
  - Each increment of strain is decomposed into **elastic and plastic parts**
  - A yield function which governs the **onset and continuance** of plastic deformation
  - A flow rule which governs the plastic flow and determines the **plastic strain increment**
  - Evolution equations for **inner properties (such as strain-hardening)** of materials



# 1D Rate-Independent Plasticity (1/3)



Stress-strain curve for typical elastic-plastic material [1]

- Decomposition of strain increments:

$$d\varepsilon = d\varepsilon^e + d\varepsilon^p$$

- Strain decomposition:

$$d\varepsilon = d\varepsilon^e + d\varepsilon^p \text{ or } \dot{\varepsilon} = \dot{\varepsilon}^e + \dot{\varepsilon}^p$$

Incremental form

Rate form (preferred for simplicity)

- Stress calculation:

$$d\sigma = E d\varepsilon^e \text{ or } \dot{\sigma} = E \dot{\varepsilon}^e$$

- Stress from whole strain:

$$d\sigma = E^{tan} d\varepsilon, \quad \dot{\sigma} = \underline{E^{tan}} \dot{\varepsilon}$$

Elastic-plastic tangent modulus

- Plastic flow potential for evolution of plastic strain:

$$\dot{\varepsilon}^p = \underline{\dot{\lambda}} \frac{\partial \Psi}{\partial \sigma}$$

Plastic rate parameter

Direction for plastic strain evolution

[1] <https://www.hindawi.com/journals/cpis/2013/267095/fig8/>



# 1D Rate-Independent Plasticity (2/3)

$$\dot{\varepsilon}^p = \dot{\lambda} \frac{\partial \Psi}{\partial \sigma}$$

- Plastic flow potential example:

$$\Psi = |\sigma| = \underline{\bar{\sigma}} = \sigma \text{sign}(\sigma)$$

1D effective stress

$$\Rightarrow \frac{\partial \Psi}{\partial \sigma} = \text{sign}(\sigma)$$

Effective plastic strain,  
one internal variable

- Yield condition:

$$f = \bar{\sigma} - \underline{\sigma_Y(\bar{\varepsilon})} = 0$$

Yield strength

Isotropic hardening – same  
tension and compression strength

- Work/strain hardening:

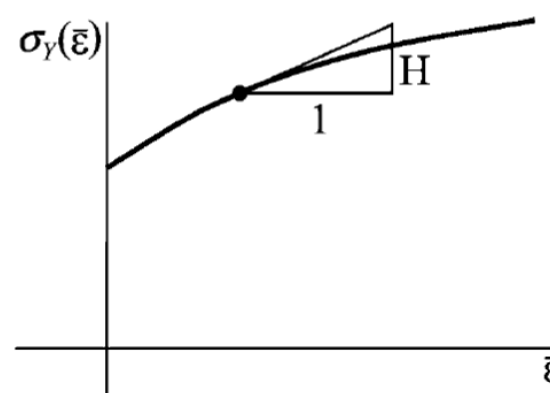
$$f = 0 \Rightarrow \sigma_Y(\bar{\varepsilon}) = \bar{\sigma}$$

$$\bar{\sigma}, \bar{\varepsilon} \uparrow \Rightarrow \sigma_Y \uparrow$$

- $\bar{\varepsilon}$  calculation for metal:

$$\bar{\varepsilon} = \int \dot{\bar{\varepsilon}} dt = \int \sqrt{\dot{\varepsilon}^p \dot{\varepsilon}^p} dt$$

- Plastic modulus:



$$H = \frac{d\sigma_Y(\bar{\varepsilon})}{d\bar{\varepsilon}}$$

# 1D Rate-Independent Plasticity (3/3)

$$\Psi = |\sigma| = \bar{\sigma} = \sigma \operatorname{sign}(\sigma)$$

$$\Rightarrow \frac{\partial \Psi}{\partial \sigma} = \operatorname{sign}(\sigma) = \frac{\partial (\bar{\sigma} - \sigma_Y(\bar{\varepsilon}))}{\partial \sigma} = \frac{\partial f}{\partial \sigma}$$

Associate plasticity for *this specific model* – plastic strain evolution direction normal to the yield surface.

$$\dot{\varepsilon} = \sqrt{\dot{\varepsilon}^p \dot{\varepsilon}^p} = \sqrt{\dot{\lambda}^2 \operatorname{sign}(\sigma)^2} = \dot{\lambda}$$

$$\Rightarrow \dot{\varepsilon}^p = \dot{\lambda} \frac{\partial \Psi}{\partial \sigma} = \dot{\varepsilon} \frac{\partial f}{\partial \sigma} = \operatorname{sign}(\sigma) \dot{\varepsilon}$$

- When plastic deformation happens,  $f = \bar{\sigma} - \sigma_Y(\bar{\varepsilon}) = 0$ , **leading to consistency condition:**

$$\dot{f} = \dot{\bar{\sigma}} - \frac{d\sigma_Y(\bar{\varepsilon})}{d\bar{\varepsilon}} \dot{\bar{\varepsilon}} = 0$$

$$\Rightarrow \dot{\bar{\sigma}} = \frac{d\sigma_Y(\bar{\varepsilon})}{d\bar{\varepsilon}} \dot{\bar{\varepsilon}} = H \dot{\bar{\varepsilon}}$$

$$\dot{\bar{\sigma}} = \dot{\sigma} \operatorname{sign}(\sigma) = H \dot{\bar{\varepsilon}} = H \dot{\varepsilon}^p \operatorname{sign}(\sigma)$$

$$\dot{\varepsilon} = \dot{\varepsilon}^e + \dot{\varepsilon}^p, \quad \dot{\sigma} = E^{tan} \dot{\varepsilon}, \quad \dot{\sigma} = E \dot{\varepsilon}^e$$

$$\Rightarrow \frac{1}{E^{tan}} = \frac{1}{E} + \frac{1}{H}$$



# Plastic switch parameter

- **Plastic switch** to change between purely elastic loading/unloading and plastic loading:

$$\frac{1}{E^{tan}} = \frac{1}{E} + \frac{1}{H} \Rightarrow E^{tan} = E - \frac{E^2}{E + H} = E - \beta \frac{E^2}{E + H} \begin{cases} \beta = 1, & \text{plastic} \\ \beta = 0, & \text{purely elastic} \end{cases}$$

- Kuhn-Tucker conditions for switch between elastic/plastic response:

➤  $\dot{\lambda} \geq 0$  – non-negative plastic rate parameter following the stress direction

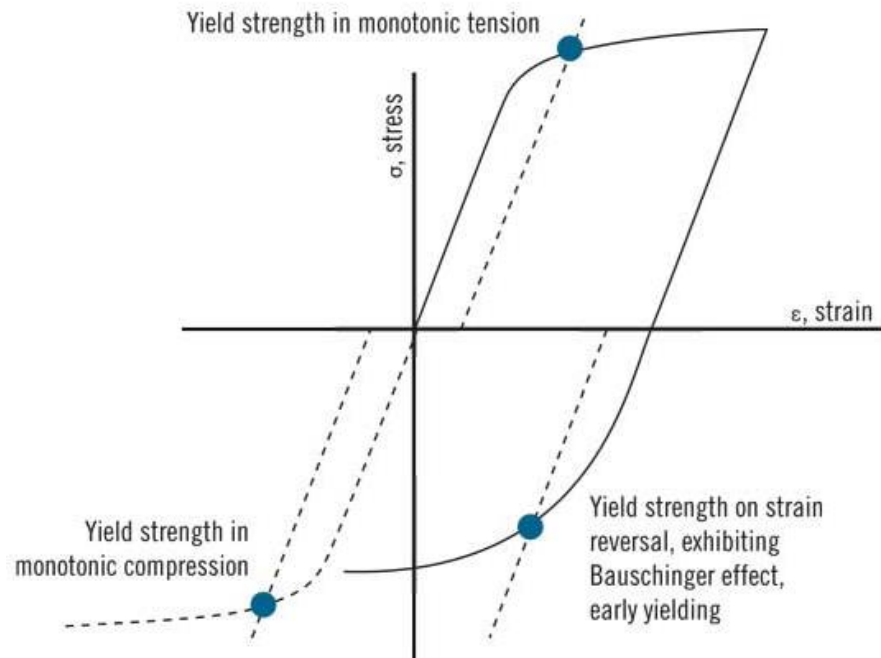
➤  $f \leq 0$  – stress state must be on or within the yield surface

➤  $\dot{\lambda} f = 0$  –

- 1) During plastic loading when  $\dot{\lambda} > 0$ , stress must be on the yield surface ( $f = 0$ )
- 2) During elastic response when  $\dot{\lambda} = 0$ , there is no plastic flow ( $f < 0$ )

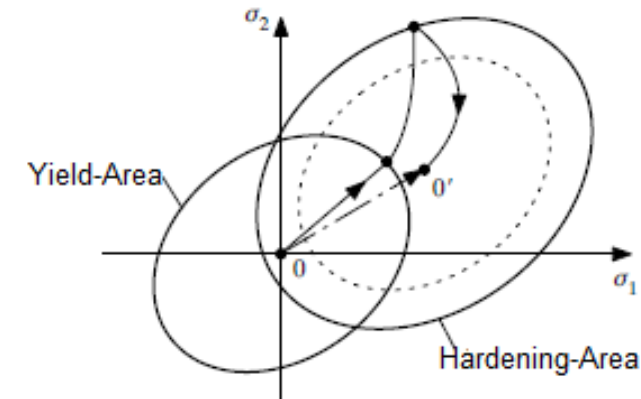
# Kinematic Hardening (1/2)

- Bauschinger effect for **cyclic plastic loading** – center of yield surface moves with plastic flow:



Stress-strain curve for Bauschinger effect [1]

- Visualization of **kinematic and isotropic** hardening:



2D yield surfaces for mixed hardening [2]

- Consideration of **1D** kinematic hardening:

$$\dot{\epsilon}^p = \dot{\lambda} \frac{\partial \Psi}{\partial \sigma}, \quad \Psi = |\sigma - \underline{\alpha}|$$

**Backstress, internal variable**

$$f = |\sigma - \underline{\alpha}| - \sigma_Y(\bar{\epsilon}) = 0$$

Effective plastic strain,  
another internal variable

[1] <https://mechanical-engg.com/blogs/entry/481-what-is-bauschinger-effect/>

[2] <https://www.dlubal.com/en/support-and-learning/support/knowledge-base/001479>



# Kinematic Hardening (2/2)

$$\Psi = |\sigma - \alpha|, \quad f = |\sigma - \alpha| - \sigma_Y(\bar{\epsilon})$$

$$\Rightarrow \frac{\partial \Psi}{\partial \sigma} = \text{sign}(\sigma - \alpha) = \frac{\partial f}{\partial \sigma}$$

Associate plasticity

$$\dot{\epsilon} = \sqrt{\dot{\epsilon}^p \dot{\epsilon}^p} = \sqrt{\dot{\lambda}^2 \text{sign}(\sigma - \alpha)^2} = \dot{\lambda}$$

$$\Rightarrow \dot{\epsilon}^p = \dot{\lambda} \frac{\partial \Psi}{\partial \sigma} = \dot{\epsilon} \frac{\partial f}{\partial \sigma} = \text{sign}(\sigma - \alpha) \dot{\epsilon}$$

- Linear kinematic hardening:

$$\dot{\alpha} = \kappa \dot{\epsilon}^p$$

- Consistency condition when yield happens:

$$\dot{f} = (\dot{\sigma} - \dot{\alpha}) \text{sign}(\sigma - \alpha) - H \dot{\epsilon} = 0$$

$$\Rightarrow \dot{\epsilon} = \frac{1}{H} (\dot{\sigma} - \dot{\alpha}) \text{sign}(\sigma - \alpha)$$

$$\dot{\sigma} = E(\dot{\epsilon} - \dot{\epsilon}^p) = E(\dot{\epsilon} - \dot{\epsilon} \text{sign}(\sigma - \alpha))$$

$$\begin{aligned} \Rightarrow (\dot{\sigma} - \dot{\alpha}) &= E(\dot{\epsilon} - \dot{\epsilon} \text{sign}(\sigma - \alpha)) - \dot{\alpha} \\ &= E(\dot{\epsilon} - \dot{\epsilon} \text{sign}(\sigma - \alpha)) - \kappa \dot{\epsilon}^p \end{aligned}$$

$$\Rightarrow \dot{\epsilon} = \frac{E \dot{\epsilon} \text{sign}(\sigma - \alpha)}{E + H + \kappa}$$

$$\Rightarrow E^{tan} = \frac{\dot{\sigma}}{\dot{\epsilon}} = \frac{E(H + \kappa)}{E + H + \kappa}$$

# Summary for 1D Rate-Independent Plasticity

- Strain rate:

$$\dot{\varepsilon} = \dot{\varepsilon}^e + \dot{\varepsilon}^p$$

- Stress rate:

$$\dot{\sigma} = E\dot{\varepsilon}^e = E(\dot{\varepsilon} - \dot{\varepsilon}^p)$$

- Plastic flow rule (*special case*):

$$\dot{\varepsilon}^p = \dot{\lambda} \frac{\partial \Psi}{\partial \sigma} = \dot{\varepsilon} \frac{\partial |\sigma - \alpha|}{\partial \sigma}$$

- Backstress (*linear kinematic hardening*):

$$\dot{\alpha} = \kappa \dot{\varepsilon}^p$$

- Yield condition:

$$f = |\sigma - \alpha| - \sigma_Y(\bar{\varepsilon}) = 0$$

- Consistency condition:

$$\dot{f} = 0 \Rightarrow \dot{\varepsilon} = \dot{\lambda} = \frac{E\dot{\varepsilon} \operatorname{sign}(\sigma - \alpha)}{E + H + \kappa}$$

- Tangent modulus:

$$E^{tan} = \frac{E(H + \kappa)}{E + H + \kappa}$$



# Multiaxial Hypoelastic-Plastic Materials (1/2)

- Elastic strains are small compared to plastic ones, causing negligible nonconservative energy error

- Decomposition of rate-of-deformation tensor:

$$\underline{\underline{D}} = \underline{\underline{D}}^e + \underline{\underline{D}}^p$$

Objective

- Hypoelastic response of a specific model with Jaumann rate Cauchy (true) stress [1]:

$$\dot{\underline{\underline{\sigma}}}^{\nabla J} = \underline{\underline{C}}_{el}^{\sigma J} : \underline{\underline{D}}^e = \underline{\underline{C}}_{el}^{\sigma J} : (\underline{\underline{D}} - \underline{\underline{D}}^p)$$

Constitutive law and objective stress measurement should be changed based on actual needs

- Rate of plastic flow:

$$\underline{\underline{D}}^p = \dot{\lambda} \underline{\underline{r}}(\underline{\underline{\sigma}}, \underline{\underline{q}}), \quad D_{ij}^p = \dot{\lambda} r_{ij}(\underline{\underline{\sigma}}, \underline{\underline{q}})$$

Plastic flow direction    Scalar plastic flow rate

- Utilization of plastic flow potential:

$$\underline{\underline{r}}(\underline{\underline{\sigma}}, \underline{\underline{q}}) = \frac{\partial \psi}{\partial \underline{\underline{\sigma}}}$$

- Typical evolution of internal variable matrix  $\underline{\underline{q}}$  (containing scalars and tensors, such as effective plastic strain and backstress):

$$\dot{\underline{\underline{q}}} = \dot{\lambda} \underline{\underline{h}}(\underline{\underline{\sigma}}, \underline{\underline{q}}), \quad \dot{q}_\alpha = \dot{\lambda} h_\alpha(\underline{\underline{\sigma}}, \underline{\underline{q}})$$

- Yield condition:

$$\dot{\lambda} \geq 0, \quad f(\underline{\underline{\sigma}}, \underline{\underline{q}}) = 0, \quad f \leq 0, \quad \dot{\lambda} f = 0$$

- Consistency condition on yield:

$$0 = \dot{f} = \frac{\partial f}{\partial \sigma_{ij}} \dot{\sigma}_{ij} + \frac{\partial f}{\partial q_\alpha} \dot{q}_\alpha \text{ or } 0 = \underline{\underline{f}}_\sigma : \dot{\underline{\underline{\sigma}}} + \underline{\underline{f}}_q \cdot \dot{\underline{\underline{q}}}$$



[1] <https://abaqus-docs.mit.edu/2017/English/SIMACAETHERefMap/simathe-c-stressrates.htm>

# Multiaxial Hypoelastic-Plastic Materials (2/2)

$$0 = \underline{f_\sigma} : \dot{\boldsymbol{\sigma}} + f_q \cdot \dot{\mathbf{q}}$$

Normal to the yield  
surface

- Associative flow rule:

$$\mathbf{r} = C f_\sigma$$

$$\mathbf{r} = \frac{\partial \psi}{\partial \boldsymbol{\sigma}} \Rightarrow \psi = C f$$

- Typical associative flow rule:

$$\psi = f, \quad \mathbf{r} = f_\sigma$$

- Property of Jaumann rate:

$$\underline{f_\sigma : \dot{\boldsymbol{\sigma}}} = \underline{f_\sigma : \boldsymbol{\sigma}^{\nabla J}}$$

Also works for other objective  
rates except the Truesdell rate

$$\Rightarrow 0 = f_\sigma : \boldsymbol{\sigma}^{\nabla J} + f_q \cdot \dot{\mathbf{q}}$$

- Calculation of scalar plastic flow rate:

$$0 = f_\sigma : \mathbf{C}_{el}^{\sigma J} : (\mathbf{D} - \mathbf{D}^p) + f_q \cdot \dot{\mathbf{q}} = f_\sigma : \mathbf{C}_{el}^{\sigma J} : (\mathbf{D} - \dot{\lambda} \mathbf{r}) + f_q \cdot \dot{\lambda} \mathbf{h}$$

$$\Rightarrow \dot{\lambda} = \frac{f_\sigma : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{-f_q \cdot \mathbf{h} + f_\sigma : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}}$$

- Definition of continuum elasto-plastic tangent modulus:

$$\begin{aligned} \boldsymbol{\sigma}^{\nabla J} &= \mathbf{C}_{el}^{\sigma J} : (\mathbf{D} - \dot{\lambda} \mathbf{r}) \\ &= \mathbf{C}_{el}^{\sigma J} : \left( \mathbf{D} - \frac{f_\sigma : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{-f_q \cdot \mathbf{h} + f_\sigma : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}} \mathbf{r} \right) = \underline{\mathbf{C}^{\sigma J}} : \mathbf{D} \end{aligned}$$

Minor symmetry due to symmetry of  $\boldsymbol{\sigma}^{\nabla J}$  and  $\mathbf{D}$

# Calculation of Tangent Modulus

$$\mathbf{C}_{el}^{\sigma J} : \left( \mathbf{D} - \frac{f_{\sigma} : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{-f_q \cdot \mathbf{h} + f_{\sigma} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}} \mathbf{r} \right) = \mathbf{C}^{\sigma J} : \mathbf{D}$$

$$\Rightarrow C_{ijkl}^{\sigma J} D_{kl} = (C_{el}^{\sigma J})_{ijkl} D_{kl} - \frac{(f_{\sigma})_{mn} (C_{el}^{\sigma J})_{mnkl} D_{kl}}{-(f_q)_{\alpha} h_{\alpha} + (f_{\sigma})_{rs} (C_{el}^{\sigma J})_{rstu} r_{tu}} (C_{el}^{\sigma J})_{ijpq} r_{pq}$$

$$\Rightarrow C_{ijkl}^{\sigma J} D_{kl} = \left[ (C_{el}^{\sigma J})_{ijkl} - \frac{(f_{\sigma})_{mn} (C_{el}^{\sigma J})_{mnkl} (C_{el}^{\sigma J})_{ijpq} r_{pq}}{-(f_q)_{\alpha} h_{\alpha} + (f_{\sigma})_{rs} (C_{el}^{\sigma J})_{rstu} r_{tu}} \right] D_{kl}$$

$$\Rightarrow C_{ijkl}^{\sigma J} = (C_{el}^{\sigma J})_{ijkl} - \frac{(f_{\sigma})_{mn} (C_{el}^{\sigma J})_{mnkl} (C_{el}^{\sigma J})_{ijpq} r_{pq}}{-(f_q)_{\alpha} h_{\alpha} + (f_{\sigma})_{rs} (C_{el}^{\sigma J})_{rstu} r_{tu}},$$

$$\mathbf{C}^{\sigma J} = \mathbf{C}_{el}^{\sigma J} - \frac{(\mathbf{C}_{el}^{\sigma J} : \mathbf{r})(f_{\sigma} : \mathbf{C}_{el}^{\sigma J})}{-f_q \cdot \mathbf{h} + f_{\sigma} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}}$$

Plastic flow contribution

Dyad (also can be denoted as  $\otimes$ ) of two 2<sup>nd</sup> order tensors for a 4<sup>th</sup> order tensor

$\mathbf{C}^{\sigma J}$  has major symmetry for associative flow due to symmetry of  $\mathbf{C}_{el}^{\sigma J}$  and  $\mathbf{r} = f_{\sigma}$



# Summary of Hypoelastic-Plastic Constitutive Law

- Deformation rate tensor (objective):

$$\mathbf{D} = \mathbf{D}^e + \mathbf{D}^p$$

- Cauchy stress with objective Jaumann rate:

$$\dot{\boldsymbol{\sigma}}^{\nabla J} = \mathbf{C}_{el}^{\sigma J} : \mathbf{D}^e = \mathbf{C}_{el}^{\sigma J} : (\mathbf{D} - \mathbf{D}^p)$$

Can be other stress rates with adjustment

- Plastic flow rule and internal variables evolution:

$$\mathbf{D}^p = \dot{\lambda} \mathbf{r}(\boldsymbol{\sigma}, \mathbf{q}), \quad \dot{\mathbf{q}} = \dot{\lambda} \mathbf{h}(\boldsymbol{\sigma}, \mathbf{q})$$

- Yield condition:

$$f(\boldsymbol{\sigma}, \mathbf{q}) = 0$$

- Loading-unloading conditions:

$$\dot{\lambda} \geq 0, \quad \dot{f} \leq 0, \quad \dot{\lambda} \dot{f} = 0$$

- Scalar plastic rate parameter:

$$\dot{\lambda} = \frac{f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{-f_{\mathbf{q}} \cdot \mathbf{h} + f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}}$$

- Stress-rate and deformation rate relation:

$$\dot{\boldsymbol{\sigma}}^{\nabla J} = \mathbf{C}^{\sigma J} : \mathbf{D}$$

$$\mathbf{C}^{\sigma J} = \mathbf{C}_{el}^{\sigma J} \text{ for elastic}$$

$$\mathbf{C}^{\sigma J} = \mathbf{C}_{el}^{\sigma J} - \frac{(\mathbf{C}_{el}^{\sigma J} : \mathbf{r})(f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J})}{-f_{\mathbf{q}} \cdot \mathbf{h} + f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}} \text{ for plastic}$$

\*This hypoelastic-plastic law needs isotropic elastic moduli and yield function, but enough for most common engineering materials – metals

# J2 Flow Theory (1/3)

- J2 flow model based on von Mises yield surface is suitable for metal plasticity

- Assume metal plastic flow is unaffected by **pressure** – supported by experiments

- Stress decomposition:

$$\boldsymbol{\sigma} = \textcolor{red}{p}\mathbf{I} + \boldsymbol{\sigma}^{dev}$$

$$\textcolor{red}{p} = \frac{1}{3} \text{trace}(\boldsymbol{\sigma}) = \frac{1}{3} \sigma_{ii}$$

- Von Mises effective stress  $\bar{\sigma}$ :

$$\bar{\sigma} = \sqrt{\frac{3}{2} \boldsymbol{\sigma}^{dev} : \boldsymbol{\sigma}^{dev}} = \sqrt{3 \textcolor{red}{J_2}} \quad \textcolor{red}{J_2} = -I_2(\boldsymbol{\sigma}^{dev}) = -\frac{1}{2} \left[ \text{tr}(\boldsymbol{\sigma}^{dev})^2 - \text{tr}(\boldsymbol{\sigma}^{dev} \cdot \boldsymbol{\sigma}^{dev}) \right] = \frac{1}{2} \boldsymbol{\sigma}^{dev} : \boldsymbol{\sigma}^{dev}$$

- Plastic flow rule:

$$\mathbf{D}^p = \dot{\lambda} \mathbf{r}(\boldsymbol{\sigma}, \mathbf{q})$$

- Internal variable – only *one* effective plastic strain:

$$\mathbf{q} = q_1 = \bar{\varepsilon} = \int \dot{\varepsilon} dt$$

- Materials are usually characterized using the **uniaxial tension** tests, when along 1 direction:

$$D_{22}^p = D_{33}^p = -\frac{1}{2} D_{11}^p$$

**Volume conservation  
in plastic deformation**

$$D_{ij} = 0, \quad i \neq j$$

# J2 Flow Theory (2/3)

$$D_{22}^p = D_{33}^p = -\frac{1}{2}D_{11}^p$$

$$D_{ij} = 0, \quad i \neq j$$

- Physical meaning of  $\mathbf{D}$  is demonstrated in [1]
- In uniaxial tension,  $D_{11}^p$  is the same as the rate of effective plastic strain:

$$D_{11}^p = \dot{\bar{\epsilon}}$$

General uniaxial  
loading condition

$$\Rightarrow \dot{\bar{\epsilon}} = \sqrt{\frac{2}{3} \mathbf{D}^p : \mathbf{D}^p}$$

Can be also obtained through:

$$\bar{\sigma} \dot{\bar{\epsilon}} = \boldsymbol{\sigma} : \mathbf{D}^p$$

- Yield condition:

$$f(\boldsymbol{\sigma}, \mathbf{q}) = \bar{\sigma} - \sigma_Y(\bar{\epsilon}) = 0$$

Associative flow rule

$$\Rightarrow f_{\boldsymbol{\sigma}} = \frac{\partial \bar{\sigma}}{\partial \boldsymbol{\sigma}} = \frac{3}{2\bar{\sigma}} \boldsymbol{\sigma}^{dev} = \mathbf{r}$$

$$\Rightarrow \mathbf{D}^p : \mathbf{D}^p = \dot{\lambda}^2 \mathbf{r} : \mathbf{r} = \dot{\lambda}^2 \frac{9}{4\bar{\sigma}^2} \boldsymbol{\sigma}^{dev} : \boldsymbol{\sigma}^{dev} = \frac{3}{2} \dot{\lambda}^2$$

$$\Rightarrow \dot{\bar{\epsilon}} = \dot{\lambda}$$

$$\dot{q}_1 = \dot{\lambda} h_1 = \dot{\bar{\epsilon}}$$

$$\Rightarrow h_1 = 1$$

# J2 Flow Theory (3/3)

- Yield condition:

$$f(\boldsymbol{\sigma}, \mathbf{q}) = \bar{\sigma} - \sigma_Y(\bar{\varepsilon}) = 0 \Rightarrow f_{\mathbf{q}} = f_{q_1} = -\frac{d\sigma_Y(\bar{\varepsilon})}{d\bar{\varepsilon}} = -H(\bar{\varepsilon})$$

Plastic modulus from  
uniaxial tension experiments

- Plastic rate parameter:

$$\dot{\lambda} = \dot{\bar{\varepsilon}} = \frac{f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{-f_{\mathbf{q}} \cdot \mathbf{h} + f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}} = \frac{f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{-f_{q_1} h_1 + f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}} = \frac{\mathbf{r} : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{H + \mathbf{r} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}}$$

- Tangent modulus:

$$\mathbf{C}^{\sigma J} = \mathbf{C}_{el}^{\sigma J} - \frac{(\mathbf{C}_{el}^{\sigma J} : \mathbf{r})(f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J})}{-f_{\mathbf{q}} \cdot \mathbf{h} + f_{\boldsymbol{\sigma}} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}} = \mathbf{C}_{el}^{\sigma J} - \frac{(\mathbf{C}_{el}^{\sigma J} : \mathbf{r})(\mathbf{r} : \mathbf{C}_{el}^{\sigma J})}{H + \mathbf{r} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}}$$

- Isotropic elastic law for the hypoelastic-plastic model:

$$\mathbf{C}_{el}^{\sigma J} = \lambda^e \delta_{ij} \delta_{kl} + \mu (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk}) \Rightarrow \mathbf{C}_{el}^{\sigma J} : \mathbf{r} = 2\mu \mathbf{r}, \quad \mathbf{r} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r} = 3\mu$$

$$\mathbf{r} = \frac{3}{2\bar{\sigma}} \boldsymbol{\sigma}^{dev} \text{ is deviatoric}$$

$$\Rightarrow \mathbf{C}^{\sigma J} = \mathbf{C}_{el}^{\sigma J} - \frac{(2\mu \mathbf{r})(2\mu \mathbf{r})}{H + 3\mu} = \mathbf{C}_{el}^{\sigma J} - \frac{4\mu^2}{H + 3\mu} \mathbf{r} \mathbf{r}$$

# Multiaxial Kinematic Hardening (1/2)

- Introduction of multiaxial backstress  $\alpha$

- Derived from J2 theory with isotropic hardening

- Definition of overall stress tensor:

$$\Sigma = \sigma - \alpha$$

- Linear hardening law for backstress evolution:

$$\alpha^{\nabla J} = \kappa D^p$$

Jaumann rate works for strain smaller than about 0.4

- Modified von Mises stress:

$$\bar{\sigma} = \sqrt{\frac{3}{2} \Sigma^{dev} : \Sigma^{dev}}$$



- Evolution of backstress as internal variable:

$$\alpha^{\nabla J} = \kappa D^p = \kappa \dot{\lambda} r(\Sigma, q)$$

- Yield condition:

$$f(\Sigma, q) = \bar{\sigma} - \sigma_Y(\bar{\epsilon}) = 0$$

$$\Rightarrow f_{\Sigma} = \frac{3}{2\bar{\sigma}} \Sigma^{dev} = r$$

Associative plasticity

$$f_{q_1} = -\frac{d\sigma_Y(\bar{\epsilon})}{d\bar{\epsilon}} = -H(\bar{\epsilon})$$

# Multiaxial Kinematic Hardening (2/2)

$$f_{\Sigma} = \frac{3}{2\bar{\sigma}} \Sigma^{dev} = \mathbf{r}, \quad f_{q_1} = -H(\bar{\epsilon}), \quad \alpha^{\nabla J} = \kappa \mathbf{D}^p = \kappa \dot{\lambda} \mathbf{r}(\Sigma, \mathbf{q})$$

- Scalar plastic rate parameter from consistency condition:

$$\dot{\lambda} = \dot{\bar{\epsilon}} = \frac{f_{\Sigma} : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{-f_{q_1} h_1 - \kappa \underline{f_{\alpha}} : \mathbf{r} + f_{\Sigma} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}} = \frac{\mathbf{r} : \mathbf{C}_{el}^{\sigma J} : \mathbf{D}}{H + \frac{3}{2} \kappa + \mathbf{r} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}}$$

$$\underline{f_{\alpha}} = f_{\sigma - \Sigma} = -f_{\Sigma} = -\mathbf{r}$$

- Continuum elasto-plastic tangent modulus:

$$\mathbf{C}^{\sigma J} = \underline{\mathbf{C}_{el}^{\sigma J}} - \frac{(\mathbf{C}_{el}^{\sigma J} : \mathbf{r})(\mathbf{r} : \mathbf{C}_{el}^{\sigma J})}{H + \frac{3}{2} \kappa + \mathbf{r} : \mathbf{C}_{el}^{\sigma J} : \mathbf{r}} = \mathbf{C}_{el}^{\sigma J} - \frac{4\mu^2}{H + \frac{3}{2} \kappa + 3\mu} \mathbf{r} \mathbf{r}$$

Isotropic for the  
hypoelastic-plastic model



# The End

