



香港中文大學
The Chinese University of Hong Kong



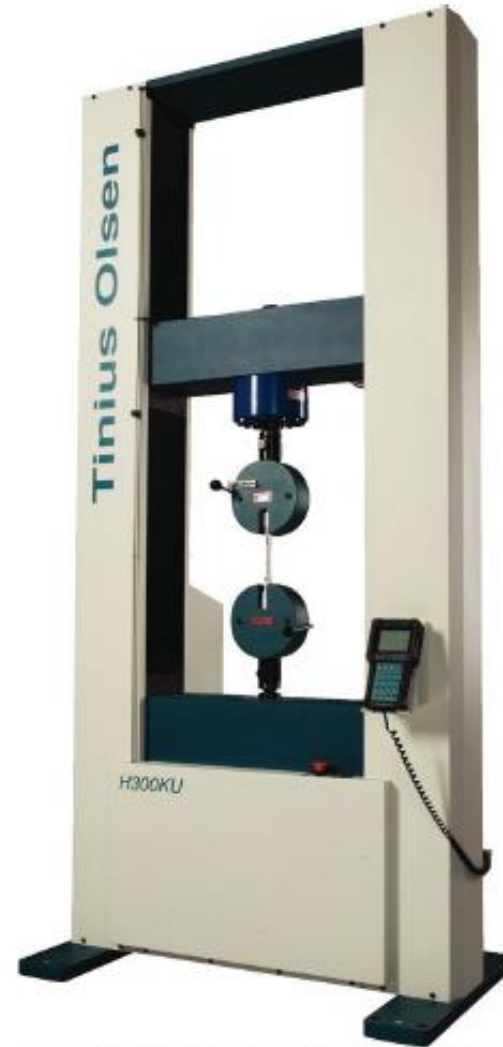
DEPARTMENT OF MECHANICAL AND
AUTOMATION ENGINEERING

14. Mechanical properties of Materials

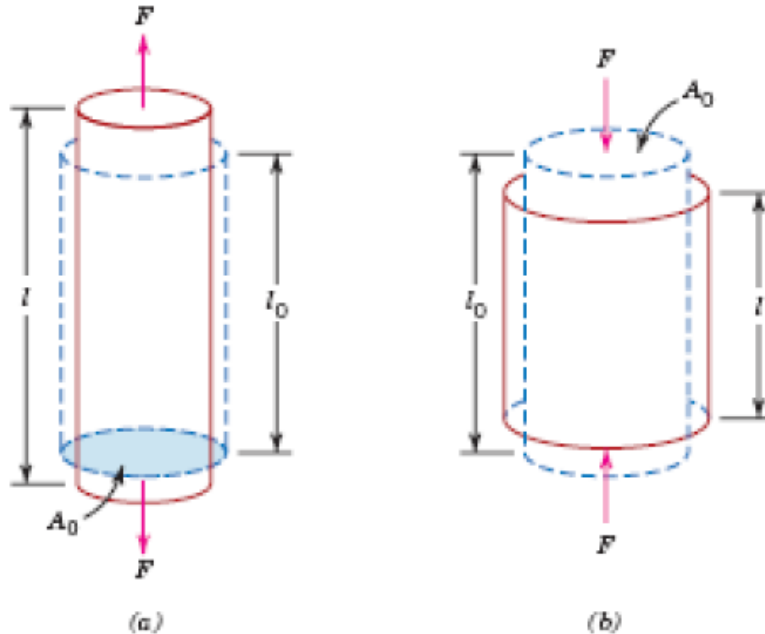


Different mechanical tests

- Tension
- Compression
- Shearing



Stress vs. Strain

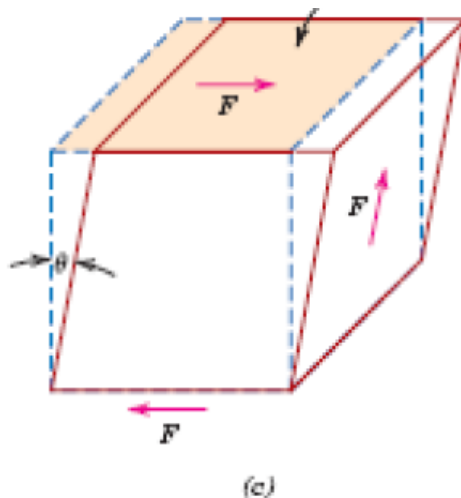


Normal stress

$$\sigma = \frac{F}{A_0}$$

Normal strain

$$\varepsilon = \frac{l - l_0}{l_0} \times 100\%$$



Shear stress

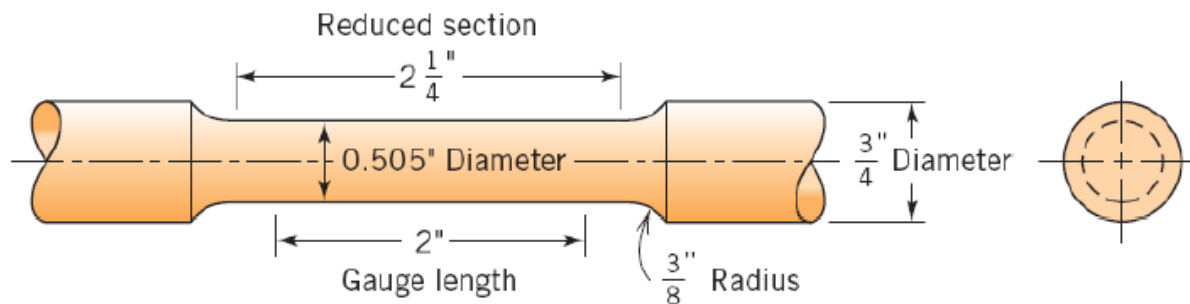
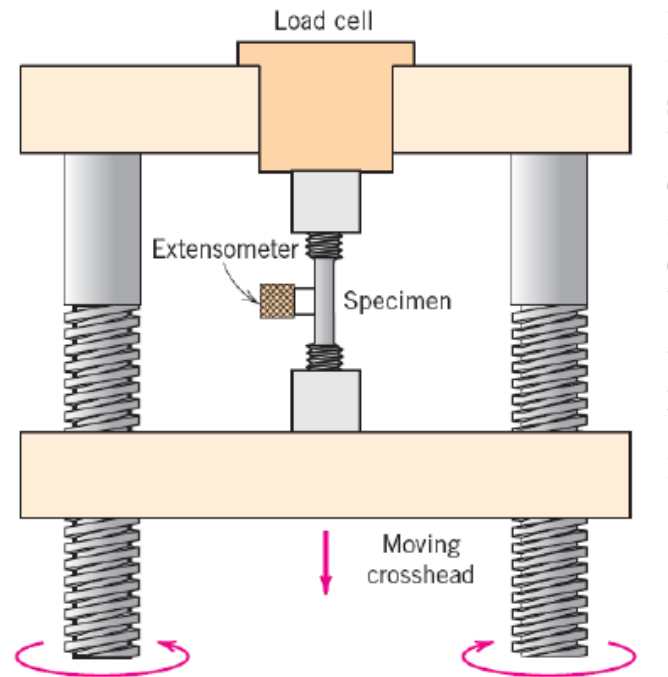
$$\tau = \frac{F}{A_0}$$

Shear strain

$$\varepsilon = \tan \theta$$

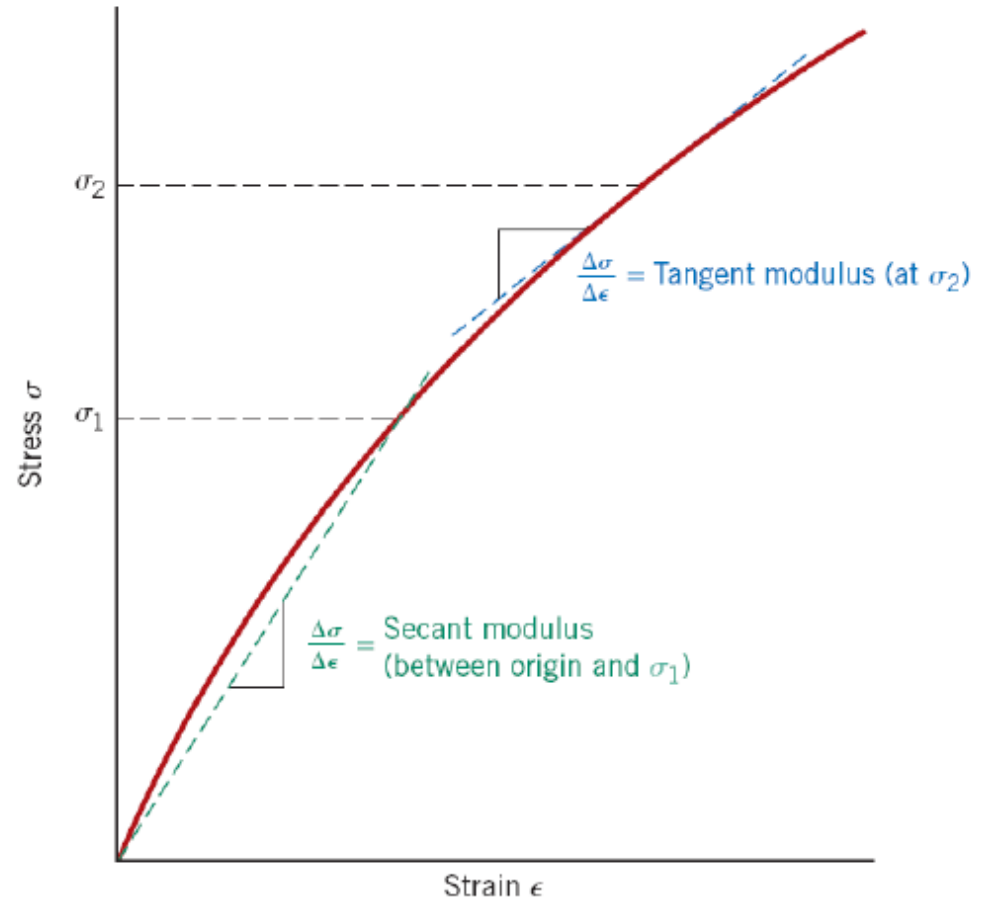
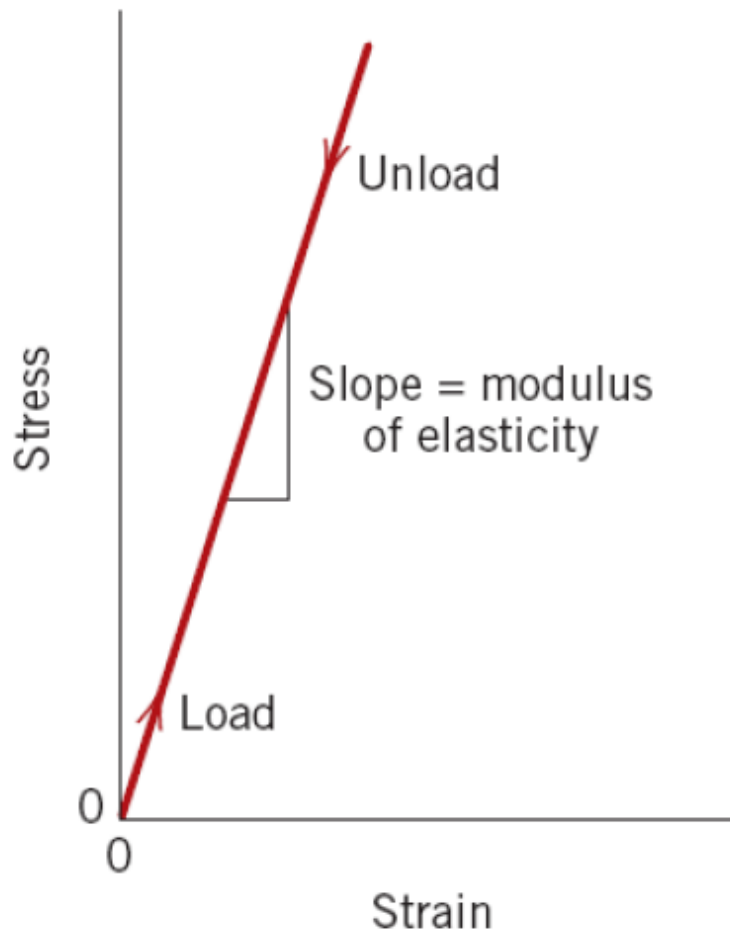


Stress-Strain diagram





Elasticity





Material	Modulus of Elasticity		Shear Modulus		Poisson's Ratio
	GPa	10 ⁶ psi	GPa	10 ⁶ psi	
Metal Alloys					
Tungsten	407	59	160	23.2	0.28
Steel	207	30	83	12.0	0.30
Nickel	207	30	76	11.0	0.31
Titanium	107	15.5	45	6.5	0.34
Copper	110	16	46	6.7	0.34
Brass	97	14	37	5.4	0.34
Aluminum	69	10	25	3.6	0.33
Magnesium	45	6.5	17	2.5	0.35
Ceramic Materials					
Aluminum oxide (Al ₂ O ₃)	393	57	—	—	0.22
Silicon carbide (SiC)	345	50	—	—	0.17
Silicon nitride (Si ₃ N ₄)	304	44	—	—	0.30
Spinel (MgAl ₂ O ₄)	260	38	—	—	—
Magnesium oxide (MgO)	225	33	—	—	0.18
Zirconia (ZrO ₂) ^a	205	30	—	—	0.31
Mullite (3Al ₂ O ₃ -2SiO ₂)	145	21	—	—	0.24
Glass-ceramic (Pyroceram)	120	17	—	—	0.25
Fused silica (SiO ₂)	73	11	—	—	0.17
Soda-lime glass	69	10	—	—	0.23
Polymers ^b					
Phenol-formaldehyde	2.76–4.83	0.40–0.70	—	—	—
Poly(vinyl chloride) (PVC)	2.41–4.14	0.35–0.60	—	—	0.38
Poly(ethylene terephthalate) (PET)	2.76–4.14	0.40–0.60	—	—	0.33
Polystyrene (PS)	2.28–3.28	0.33–0.48	—	—	0.33
Poly(methyl methacrylate) (PMMA)	2.24–3.24	0.33–0.47	—	—	0.37–0.44
Polycarbonate (PC)	2.38	0.35	—	—	0.36
Nylon 6,6	1.59–3.79	0.23–0.55	—	—	0.39
Polypropylene (PP)	1.14–1.55	0.17–0.23	—	—	0.40
Polyethylene—high density (HDPE)	1.08	0.16	—	—	0.46
Polytetrafluoroethylene (PTFE)	0.40–0.55	0.058–0.080	—	—	0.46
Polyethylene—low density (LDPE)	0.17–0.28	0.025–0.041	—	—	0.33–0.40

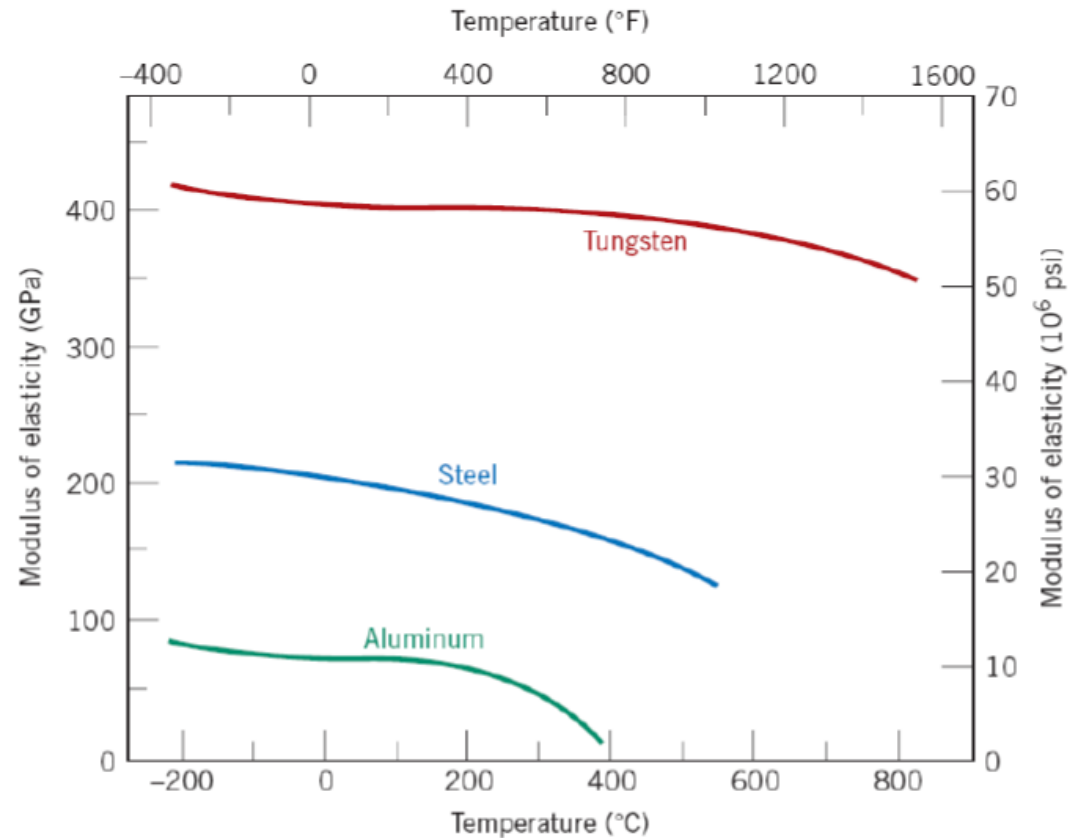
^aPartially stabilized with 3 mol% Y₂O₃.

^bModern Plastics Encyclopedia '96, McGraw-Hill, New York, 1995.



Temperature-dependent modulus

Figure 6.8 Plot of modulus of elasticity versus temperature for tungsten, steel, and aluminum. (Adapted from K. M. Ralls, T. H. Courtney, and J. Wulff, *Introduction to Materials Science and Engineering*. Copyright © 1976 by John Wiley & Sons, New York. Reprinted by permission of John Wiley & Sons, Inc.)



Temperature ↑

Atomic vibration ↑

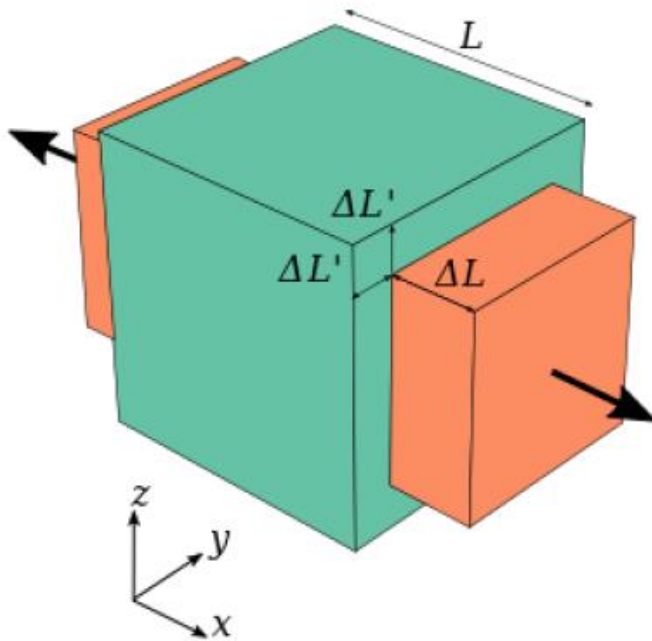
Atomic distance ↓

Atomic force ↓

Modulus ↓



Poisson's Ratio



$$d\varepsilon_x = \frac{dx}{x} \quad d\varepsilon_y = \frac{dy}{y} \quad d\varepsilon_z = \frac{dz}{z}$$

$$-\nu \int_L^{L+\Delta L} \frac{dx}{x} = \int_L^{L+\Delta L'} \frac{dy}{y} = \int_L^{L+\Delta L'} \frac{dz}{z}$$

$$\left(1 + \frac{\Delta L}{L}\right)^{-\nu} = 1 + \frac{\Delta L'}{L}$$

$$\nu \approx -\frac{\Delta L'}{\Delta L}$$



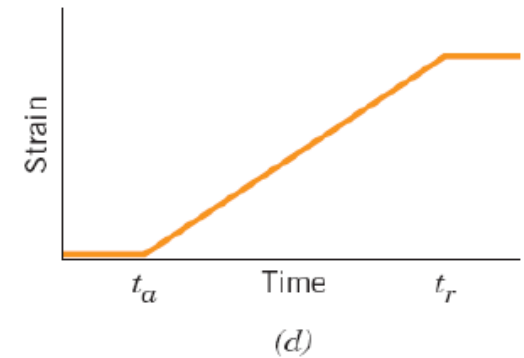
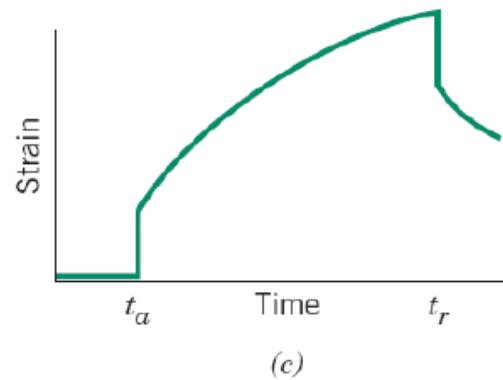
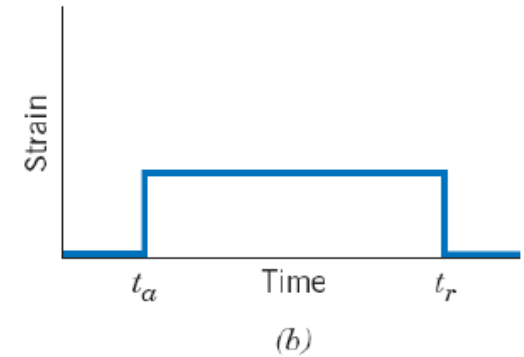
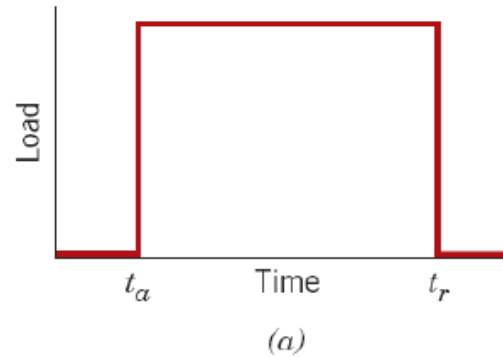
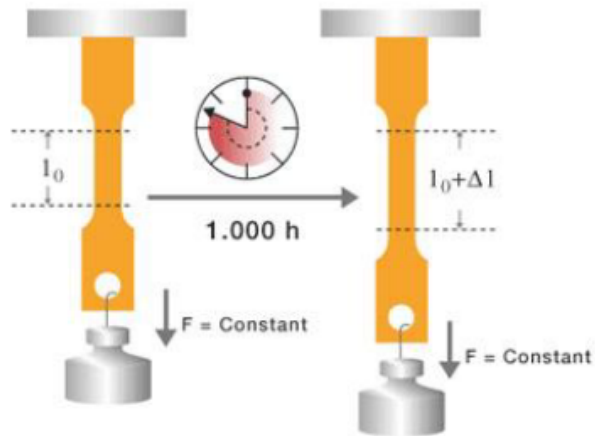
Inelasticity

Elastic deformation can be time-dependent:

- With constant stress, the strain may further increase;
- After stress is removed, strain goes back to zero after a while;
- For polymers, such time-dependent behavior is significant: **Viscoelasticity**



Viscoelasticity: Creep

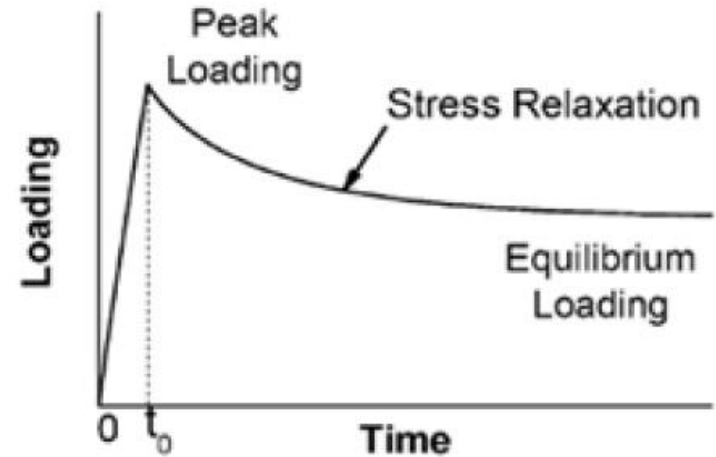
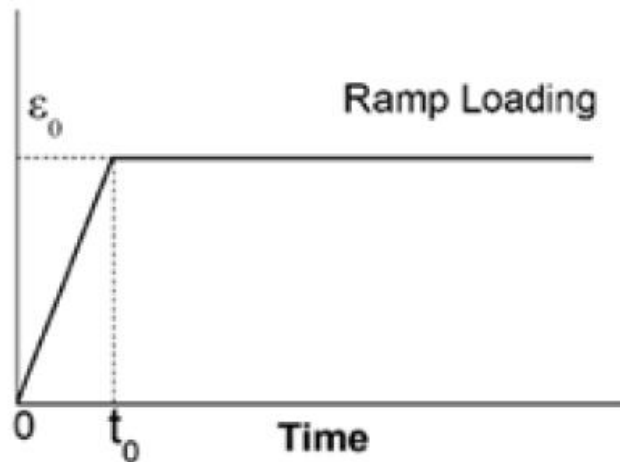




Viscoelasticity: Relaxation



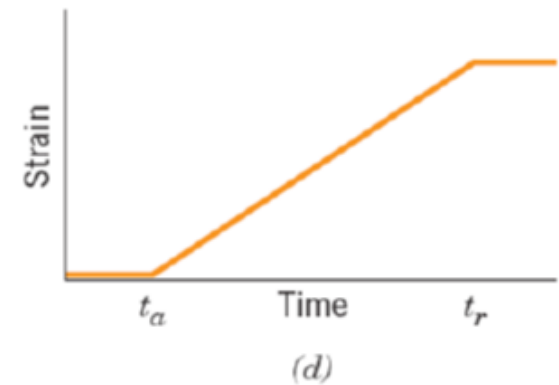
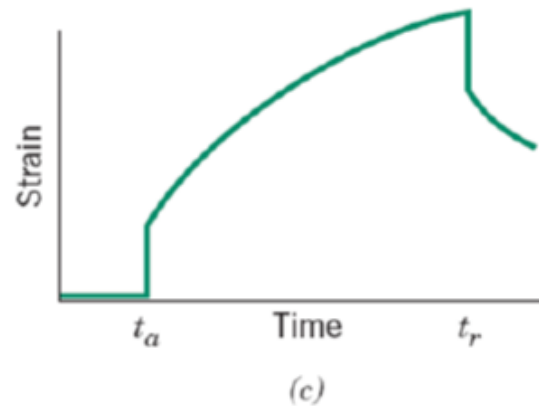
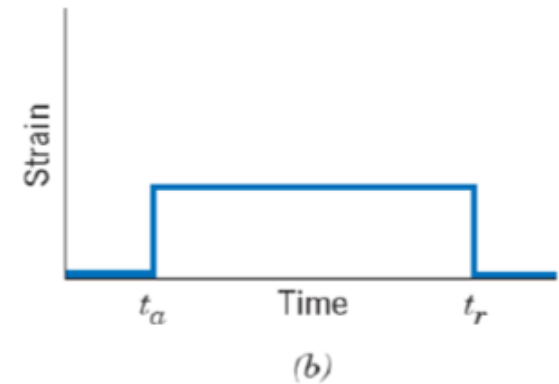
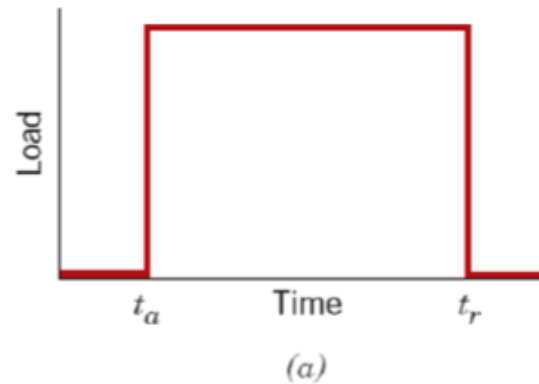
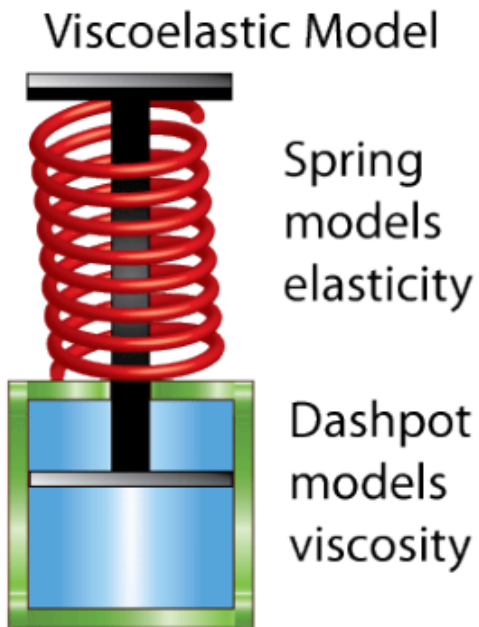
Fix deformation





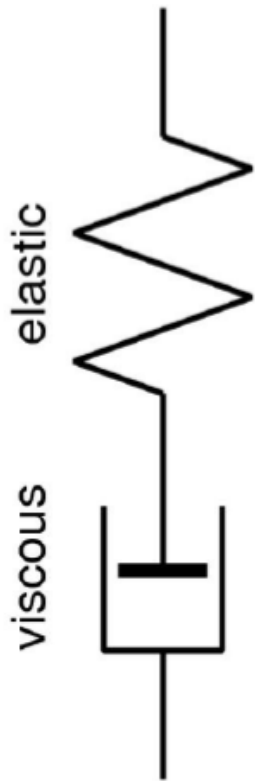
Spring dashpot for viscoelasticity

Conceptual model





Viscoelasticity Model



$$\sigma_{\text{Total}} = \sigma_D = \sigma_S$$

$$\varepsilon_{\text{Total}} = \varepsilon_D + \varepsilon_S$$

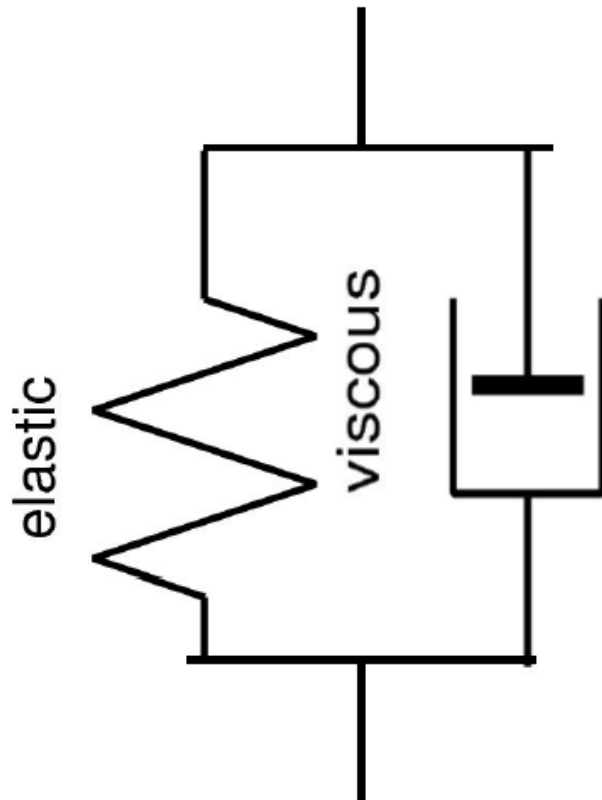
$$\frac{d\varepsilon_{\text{Total}}}{dt} = \frac{d\varepsilon_D}{dt} + \frac{d\varepsilon_S}{dt} = \frac{\sigma}{\eta} + \frac{1}{E} \frac{d\sigma}{dt}$$

$$\frac{\dot{\sigma}}{E} + \frac{\sigma}{\eta} = \dot{\varepsilon}$$

Maxwell model



Viscoelasticity Model



$$\varepsilon_{\text{Total}} = \varepsilon_S = \varepsilon_D$$

$$\sigma_{\text{Total}} = \sigma_S + \sigma_D$$

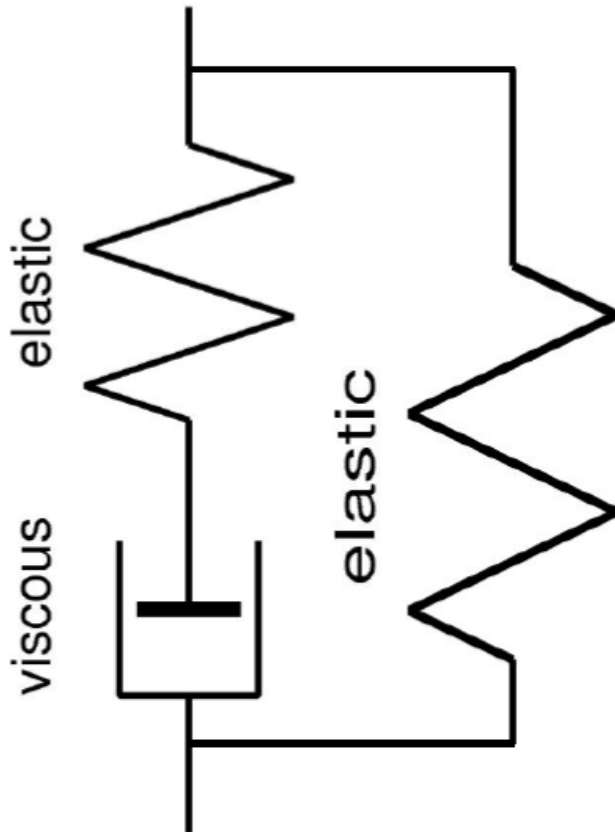
$$\sigma(t) = E\varepsilon(t) + \eta \frac{d\varepsilon(t)}{dt}$$

$$\sigma = E\varepsilon + \eta\dot{\varepsilon}$$

Kelvin-Voigt model



Viscoelasticity Model



Zener model

$$\sigma_{tot} = \sigma_m + \sigma_{S_1}$$

$$\varepsilon_{tot} = \varepsilon_m = \varepsilon_{S_1}$$

$$\sigma_m = \sigma_D = \sigma_{S_2}$$

$$\varepsilon_m = \varepsilon_D + \varepsilon_{S_2}$$

$$\frac{d\varepsilon(t)}{dt} = \frac{\frac{E_2}{\eta} \left(\frac{\eta}{E_2} \frac{d\sigma(t)}{dt} + \sigma(t) - E_1 \varepsilon(t) \right)}{E_1 + E_2}$$

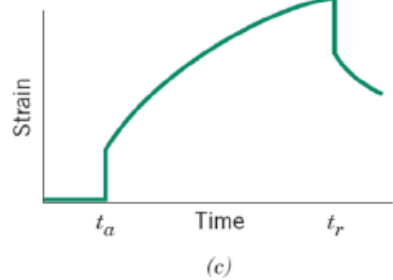
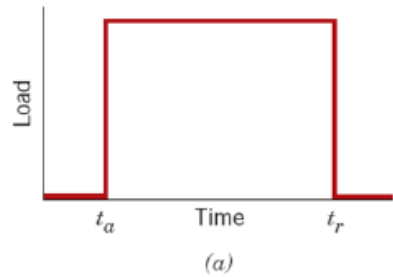
$$\sigma(t) + \frac{\eta}{E_2} \frac{d\sigma(t)}{dt} = E_1 \varepsilon(t) + \frac{\eta(E_1 + E_2)}{E_2} \frac{d\varepsilon(t)}{dt}$$

$$\sigma + \frac{\eta}{E_1 + E_2} \dot{\sigma} = \frac{E_1 E_2}{E_1 + E_2} \varepsilon + \frac{E_1 \eta}{E_1 + E_2} \dot{\varepsilon}$$

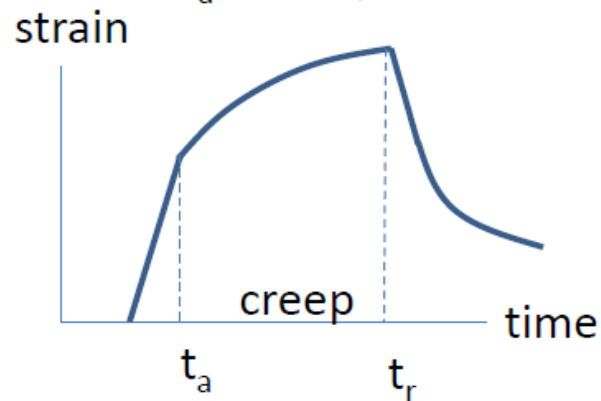
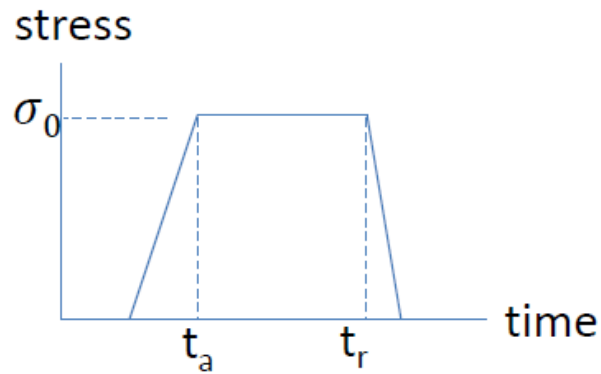


Creep experiment

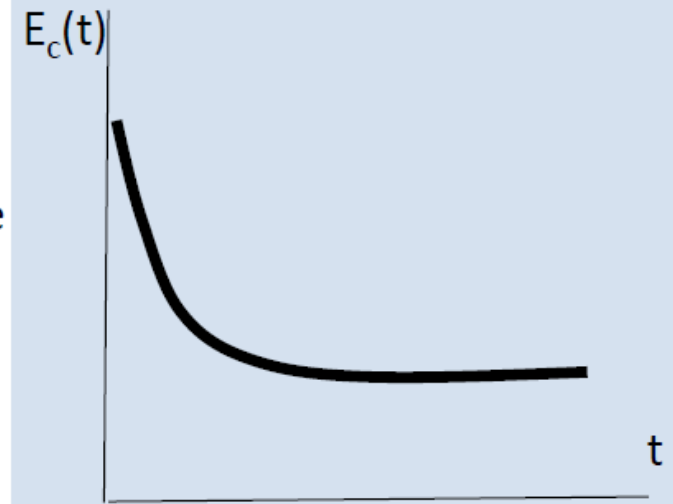
Ideal case



Real experiment



Creep modulus

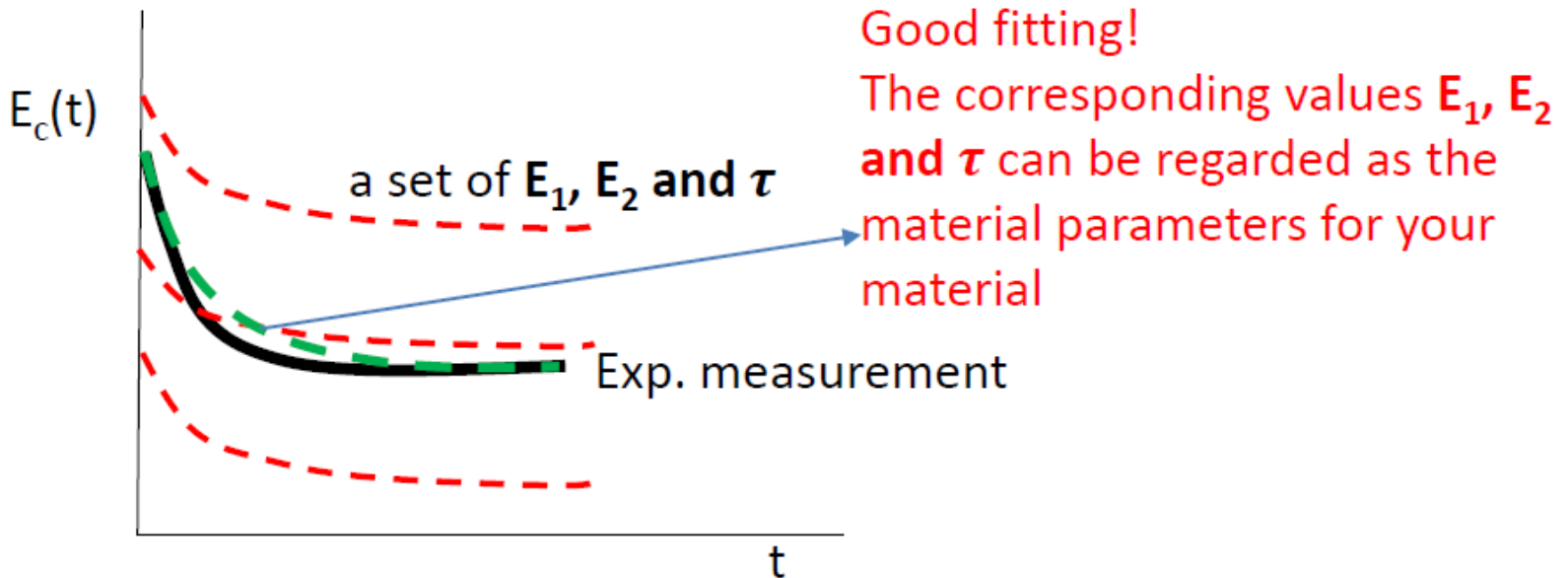




Data fittings

Zener model:
$$E_c(t) = \frac{1}{\frac{1}{E_1 + E_2} + \left(\frac{1}{E_1} - \frac{1}{E_1 + E_2} \right) \left(1 - \exp\left(-\frac{t}{\tau}\right) \right)}$$

Selecting a group of material parameters: E_1 , E_2 and τ , to make the prediction of the model close to experimental measurements





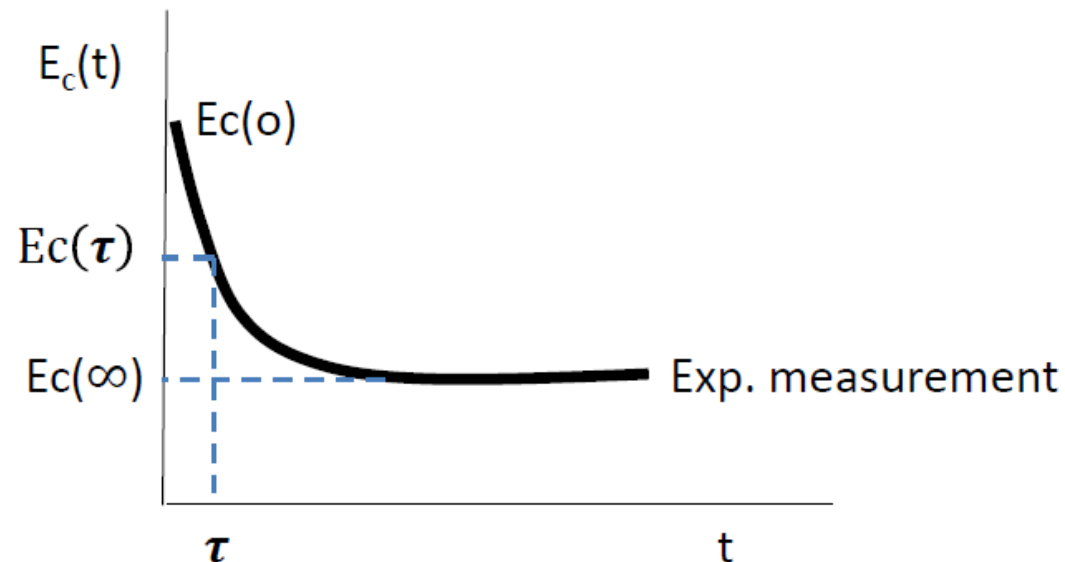
Rough estimations of material parameters in the model

$$E_c(t) = \frac{1}{\frac{1}{E_1 + E_2} + \left(\frac{1}{E_1} - \frac{1}{E_1 + E_2} \right) \left(1 - \exp\left(-\frac{t}{\tau}\right) \right)},$$

When $t=0$, $E_c(0) = E_1 + E_2$;

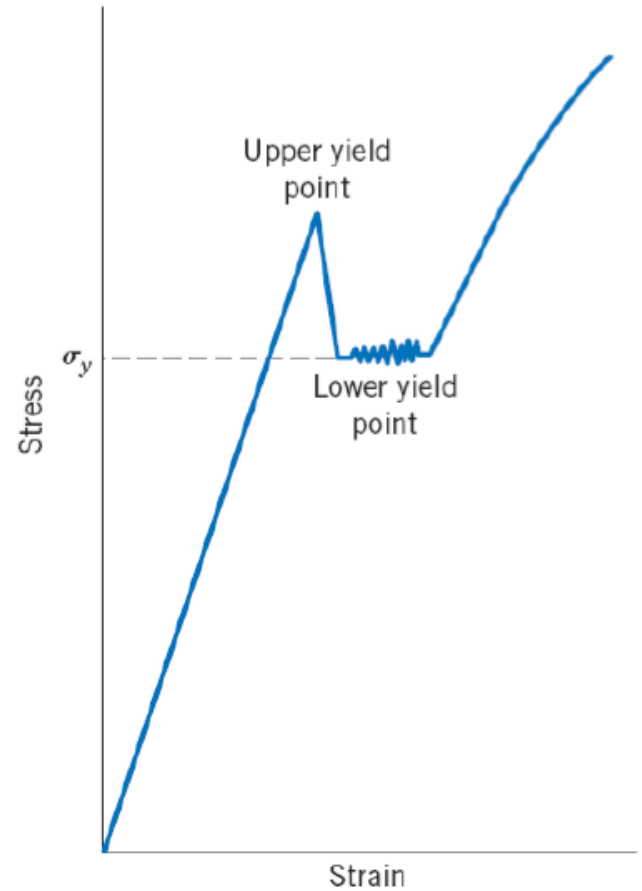
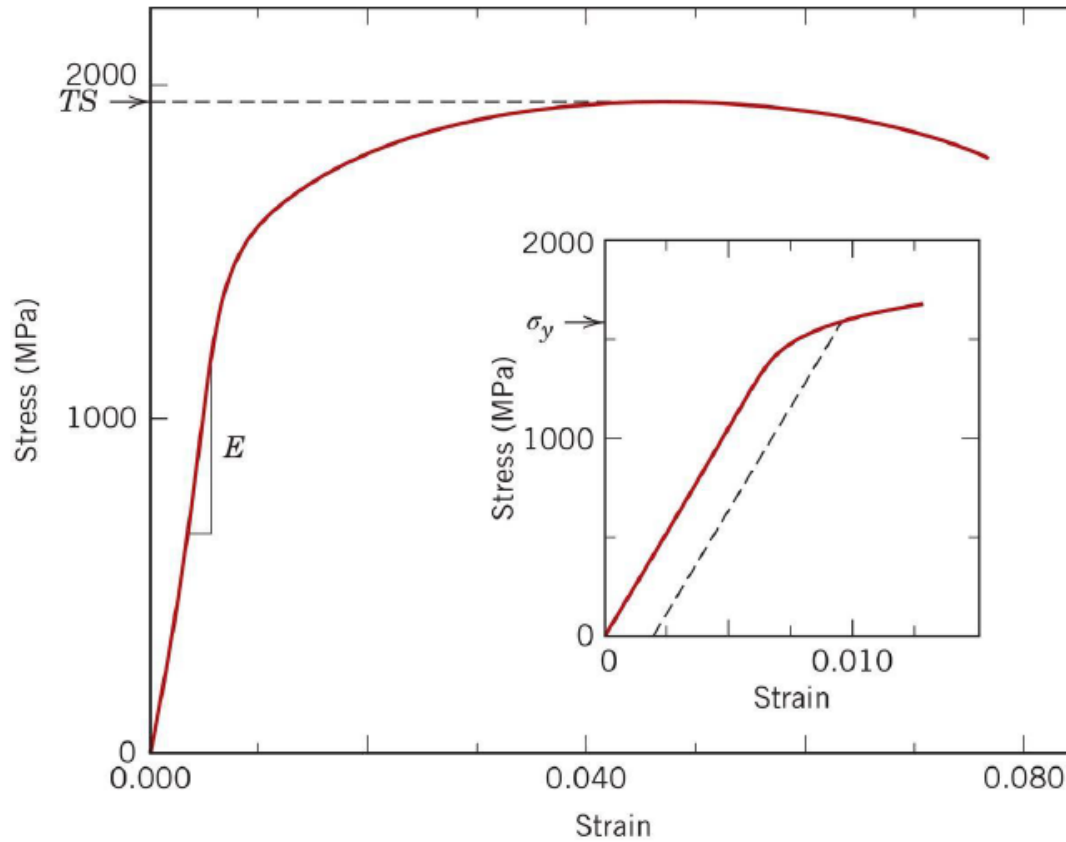
when $t=\infty$, $E_c(\infty) = E_1$;

When $t = \tau$, $E_c(\tau) = (E_1 + E_2) / (1 + (1 - e^{-1})(E_2 / E_1))$;



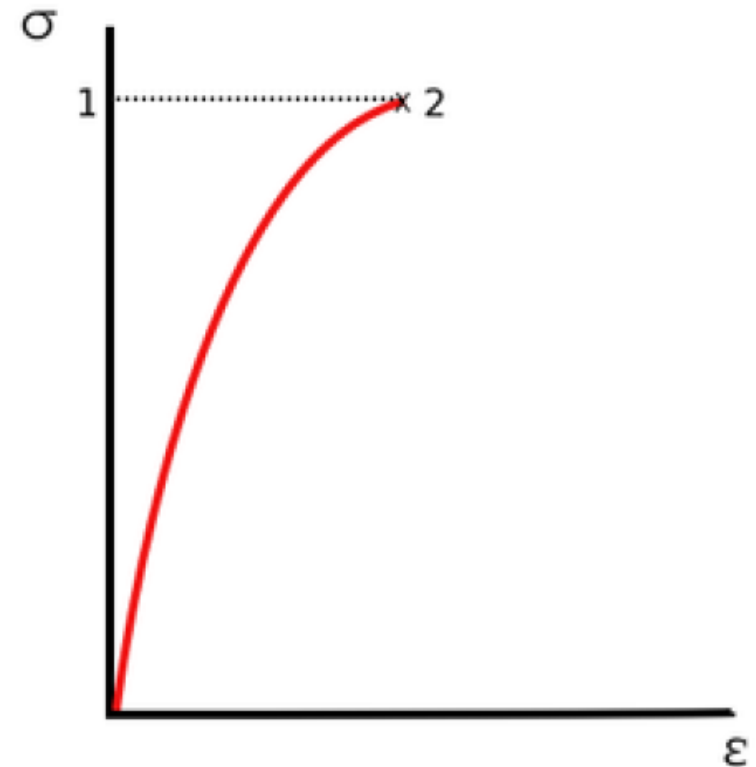
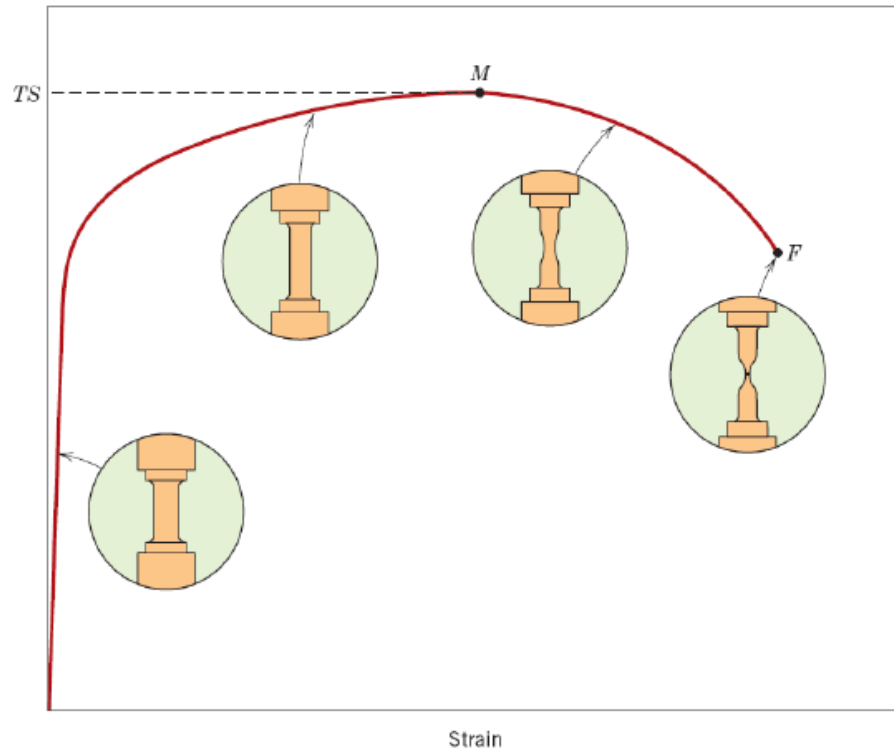


Plastic deformation



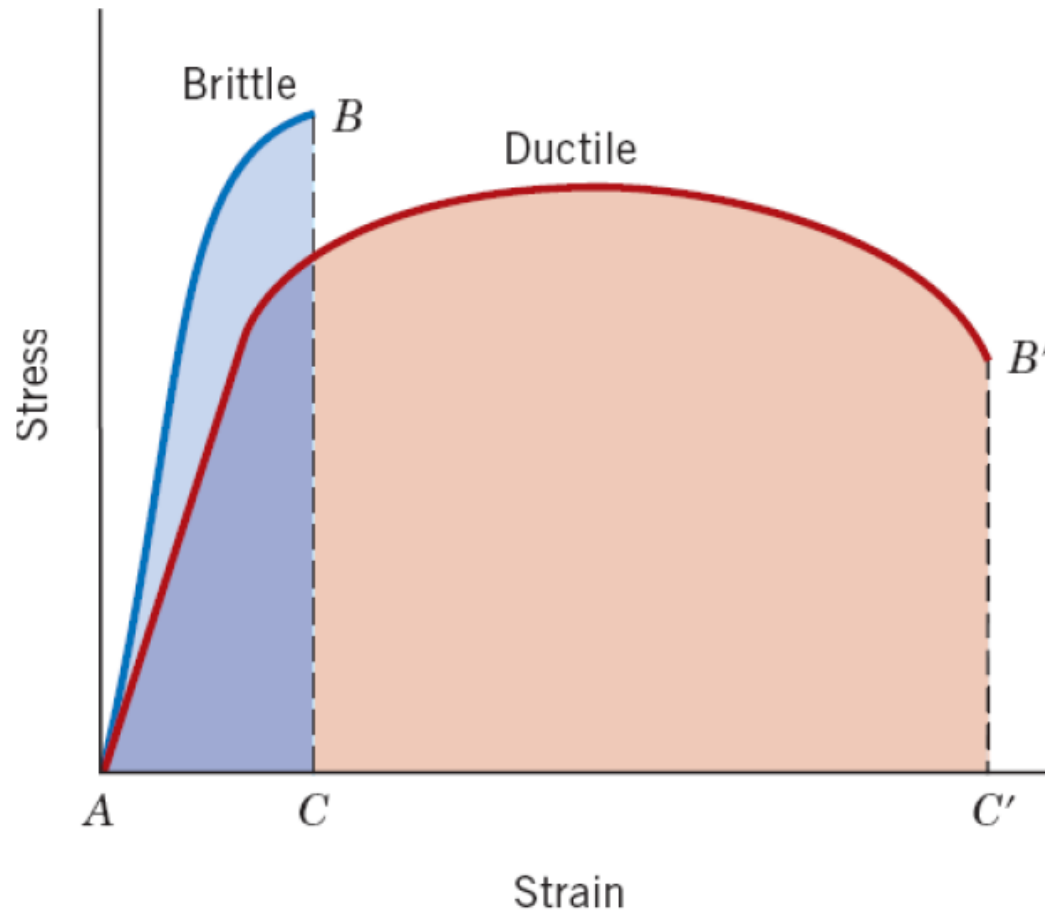


Strength





Ductility, Resilience and Toughness





Ductility, Resilience and Toughness

Material	Yield Strength		Tensile Strength		Ductility, %EL [in 50 mm (2 in.)] ^a
	MPa	ksi	MPa	ksi	
Metal Alloys ^b					
Molybdenum	565	82	655	95	35
Titanium	450	65	520	75	25
Steel (1020)	180	26	380	55	25
Nickel	138	20	480	70	40
Iron	130	19	262	38	45
Brass (70 Cu–30 Zn)	75	11	300	44	68
Copper	69	10	200	29	45
Aluminum	35	5	90	13	40
Ceramic Materials ^c					
Zirconia (ZrO ₂) ^d	—	—	800–1500	115–215	—
Silicon nitride (Si ₃ N ₄)	—	—	250–1000	35–145	—
Aluminum oxide (Al ₂ O ₃)	—	—	275–700	40–100	—
Silicon carbide (SiC)	—	—	100–820	15–120	—
Glass–ceramic (Pyroceram)	—	—	247	36	—
Mullite (3Al ₂ O ₃ –2SiO ₂)	—	—	185	27	—
Spinel (MgAl ₂ O ₄)	—	—	110–245	16–36	—
Fused silica (SiO ₂)	—	—	110	16	—
Magnesium oxide (MgO) ^e	—	—	105	15	—
Soda–lime glass	—	—	69	10	—
Polymers					
Nylon 6,6	44.8–82.8	6.5–12	75.9–94.5	11.0–13.7	15–300
Polycarbonate (PC)	62.1	9.0	62.8–72.4	9.1–10.5	110–150
Poly(ethylene terephthalate) (PET)	59.3	8.6	48.3–72.4	7.0–10.5	30–300
Poly(methyl methacrylate) (PMMA)	53.8–73.1	7.8–10.6	48.3–72.4	7.0–10.5	2.0–5.5
Poly(vinyl chloride) (PVC)	40.7–44.8	5.9–6.5	40.7–51.7	5.9–7.5	40–80
Phenol-formaldehyde	—	—	34.5–62.1	5.0–9.0	1.5–2.0
Polystyrene (PS)	25.0–69.0	3.63–10.0	35.9–51.7	5.2–7.5	1.2–2.5
Polypropylene (PP)	31.0–37.2	4.5–5.4	31.0–41.4	4.5–6.0	100–600
Polyethylene—high density (HDPE)	26.2–33.1	3.8–4.8	22.1–31.0	3.2–4.5	10–1200
Polytetrafluoroethylene (PTFE)	13.8–15.2	2.0–2.2	20.7–34.5	3.0–5.0	200–400
Polyethylene—low density (LDPE)	9.0–14.5	1.3–2.1	8.3–31.4	1.2–4.55	100–650

^aFor polymers, percent elongation at break.

^bProperty values are for metal alloys in an annealed state.

^cThe tensile strength of ceramic materials is taken as flexural strength (Section 7.10).

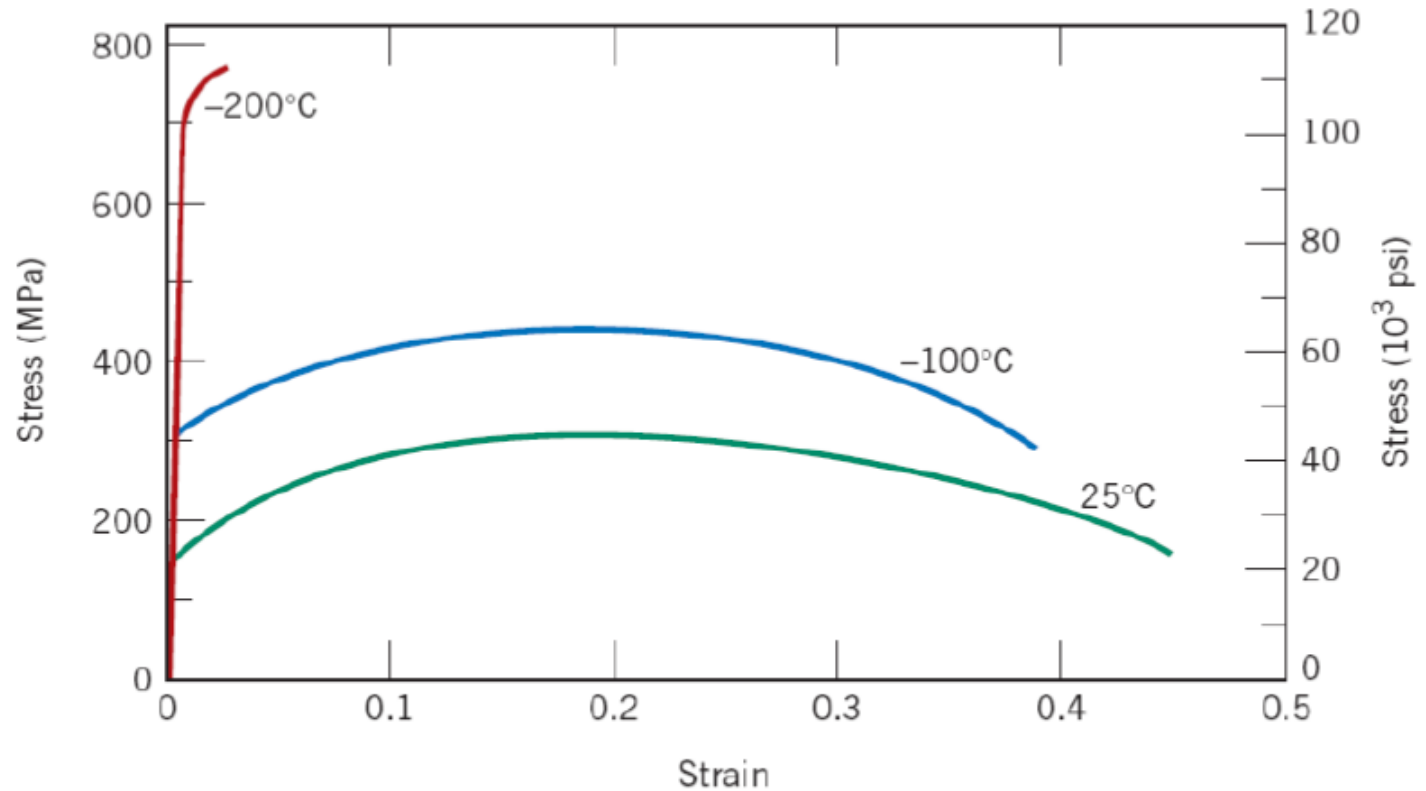
^dPartially stabilized with 3 mol% Y₂O₃.

^eSintered and containing approximately 5% porosity.



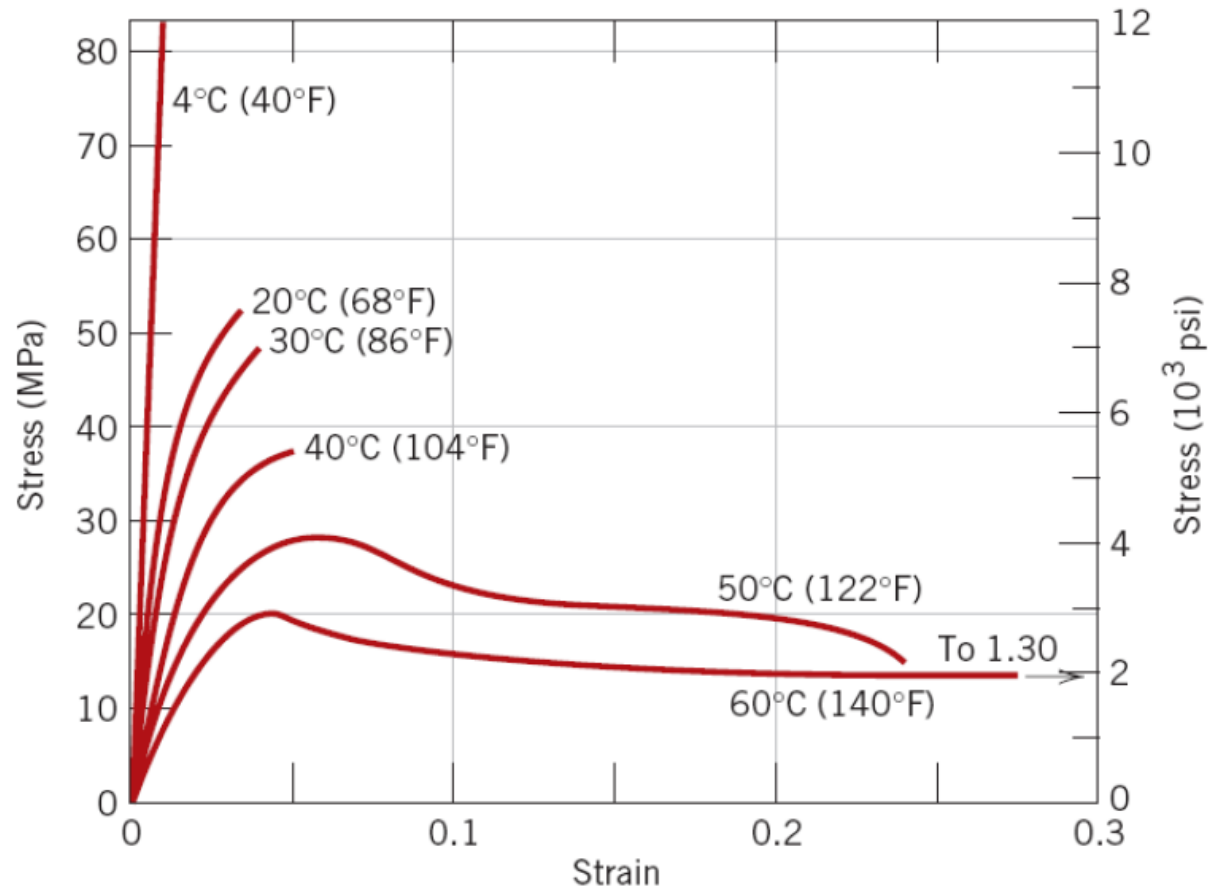
Temperature-dependent mechanical properties

Figure 6.14
Engineering stress–
strain behavior
for iron at three
temperatures.





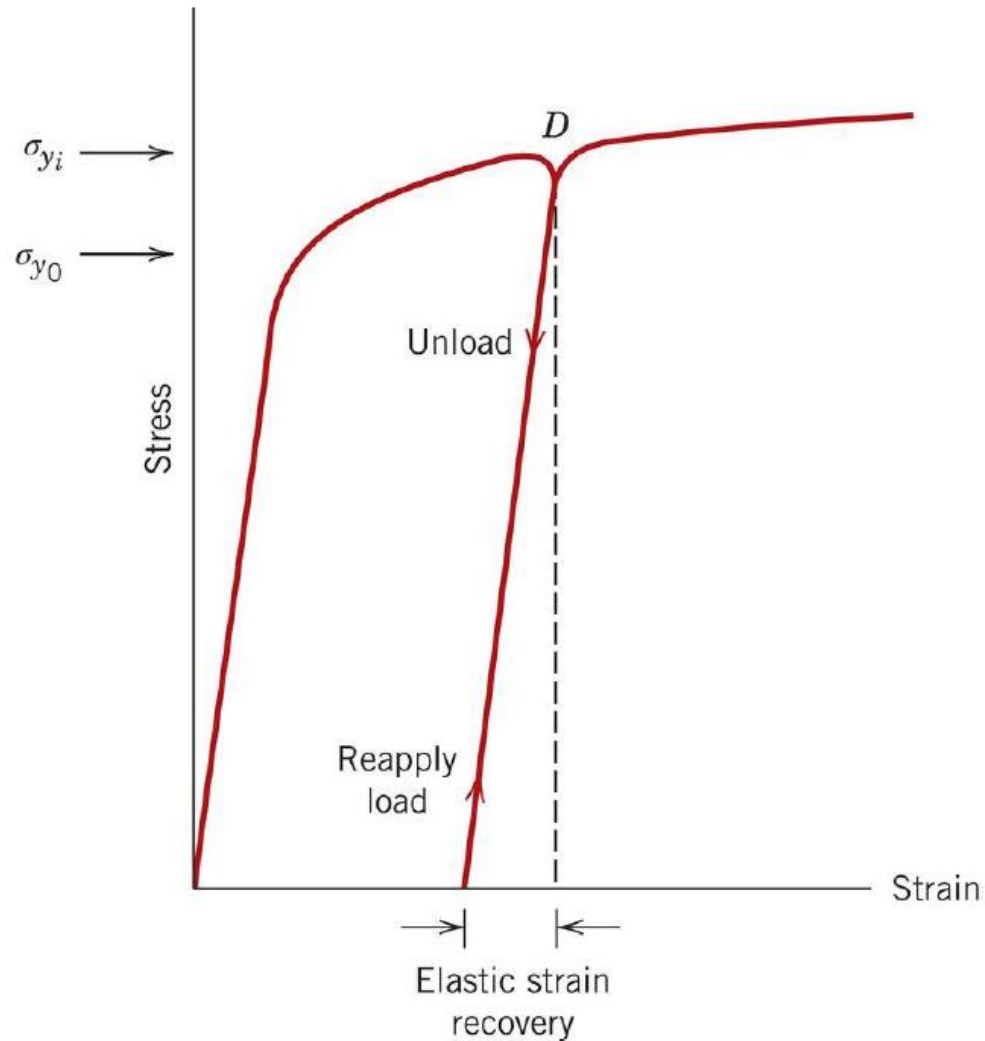
Temperature-dependent mechanical properties



PMMA

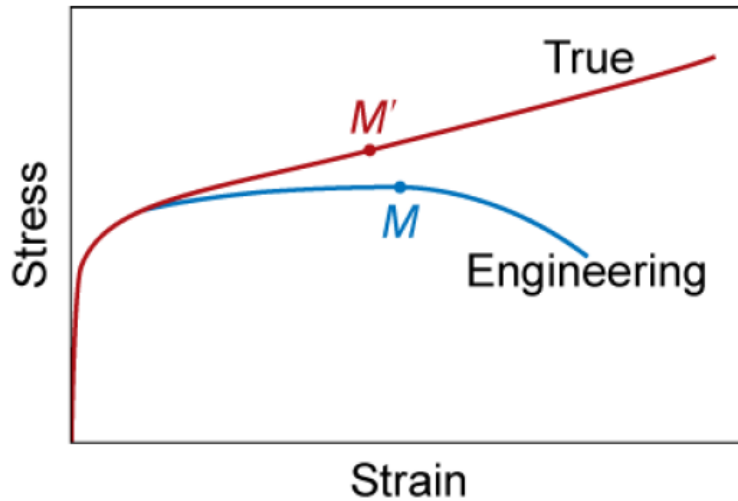


Elastic recovery after plastic deformation





True stress and true strain

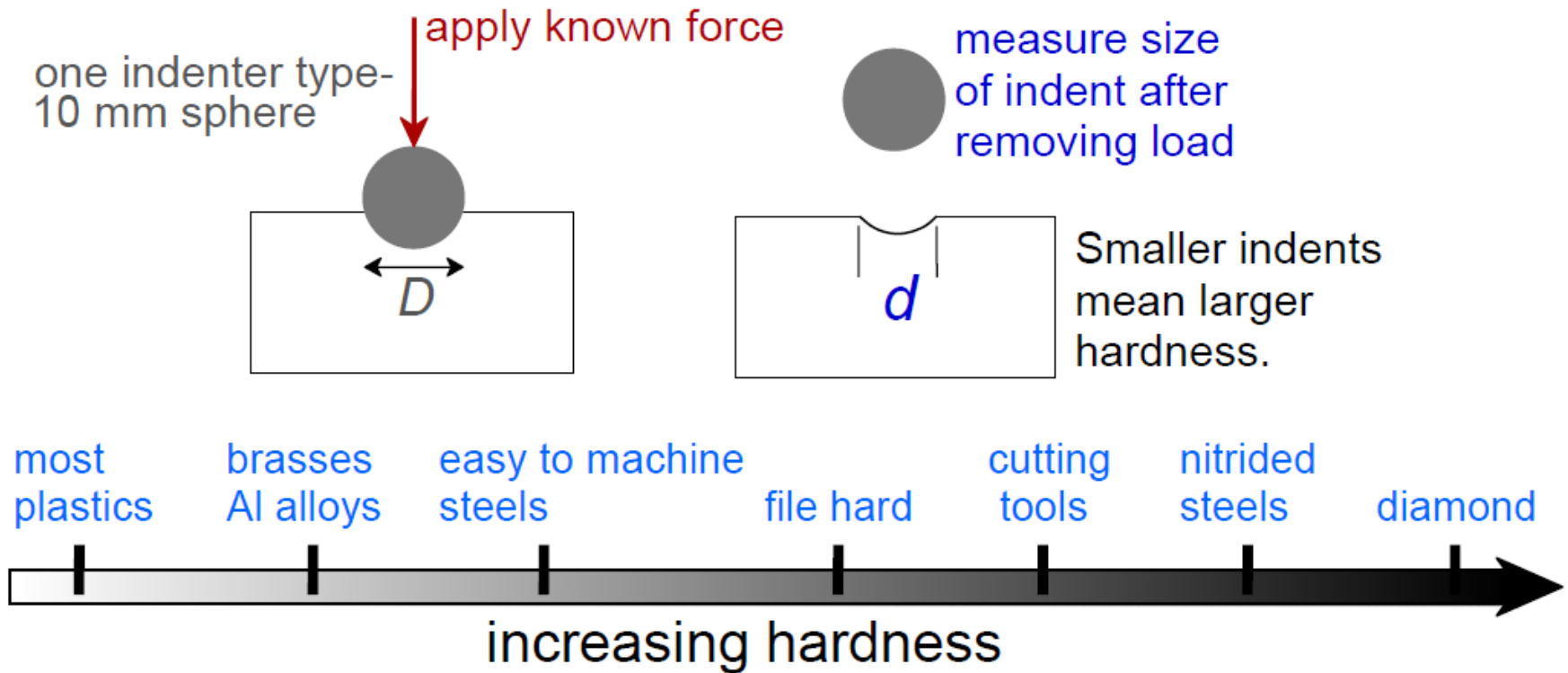


$$\sigma_T = K(\epsilon_T)^n$$

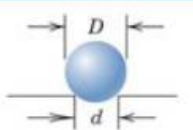



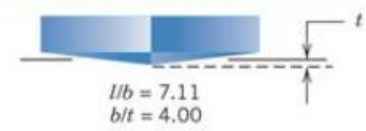
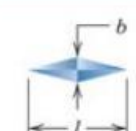
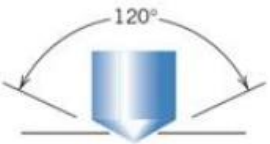



Material	<i>n</i>	<i>K</i>	
		MPa	psi
Low-carbon steel (annealed)	0.21	600	87,000
4340 steel alloy (tempered at 315°C)	0.12	2650	385,000
304 stainless steel (annealed)	0.44	1400	205,000
Copper (annealed)	0.44	530	76,500
Naval brass (annealed)	0.21	585	85,000
2024 aluminum alloy (heat-treated—T3)	0.17	780	113,000
AZ-31B magnesium alloy (annealed)	0.16	450	66,000



Hardness



Hardness

Test	Indenter	Shape of Indentation		Load	Formula for Hardness Number ^a
		Side View	Top View		
Brinell	10-mm sphere of steel or tungsten carbide			P	$HB = \frac{2P}{\pi D [D - \sqrt{D^2 - d^2}]}$
Vickers microhardness	Diamond pyramid			P	$HV = 1.854P/d_1^2$
Knoop microhardness	Diamond pyramid			P	$HK = 14.2 P/l^2$
Rockwell and superficial Rockwell	{ Diamond cone; $\frac{1}{16}$ -, $\frac{1}{8}$ -, $\frac{1}{4}$ -, $\frac{1}{2}$ - in. diameter tungsten carbide spheres }	 	 	{ 60 kg 100 kg 150 kg } Rockwell { 15 kg 30 kg 45 kg } Superficial Rockwell	

^aFor the hardness formulas given, P (the applied load) is in kg and D , d , d_1 , and l are all in mm.

Source: Adapted from H. W. Hayden, W. G. Moffatt, and J. Wulff, *The Structure and Properties of Materials*, Vol. III, *Mechanical Behavior*. Copyright © 1965 by John Wiley & Sons, New York. Reprinted by permission of John Wiley & Sons, Inc.



Variability of Material Properties

- Statistical treatments
- Typical value—take **average value**, \bar{X} for some parameter x :

n = number of measurements

x_i = specific measured value

$$\bar{X} = \frac{\sum_{i=1}^n x_i}{n}$$

- Degree of scatter—use **standard deviation**, s
- $$s = \left[\frac{\sum_{i=1}^n (x_i - \bar{X})^2}{n - 1} \right]^{\frac{1}{2}}$$



Design/Safety Factors

- Because of design uncertainties allowances must be made to protect against unanticipated failure
- For structural applications, to protect against possibility of failure—use working stress, σ_w , and a factor of safety, N

$$\sigma_w = \frac{\sigma_y}{N}$$

yield strength

Depending on application,
 N is between 1.2 and 4



Design/Safety Factors

Example Problem: A cylindrical rod, to be constructed from a steel that has a yield strength of 310 MPa, is to withstand a load of 220,000 N without yielding. Assuming a value of 4 for N , specify a suitable bar diameter.

$$\sigma_w = \frac{\sigma_y}{N}$$
$$\frac{220,000 \text{ N}}{\pi \left(\frac{d}{2} \right)^2} = \frac{310 \text{ MPa}}{4}$$

Steel rod: $\sigma_y = 310 \text{ MPa}$

Solving for the rod diameter d yields

$$d = 0.060 \text{ m} = 60 \text{ mm}$$

Fracture Phenomena

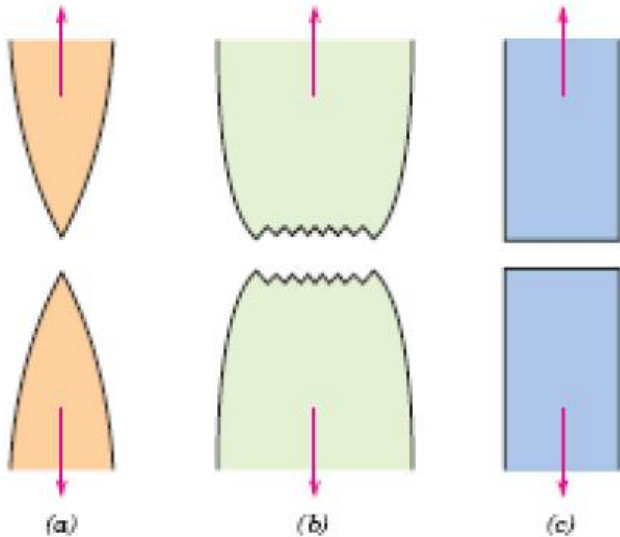


Figure 8.3 (a) Cup-and-cone fracture in aluminum. (b) Brittle fracture in a mild steel.

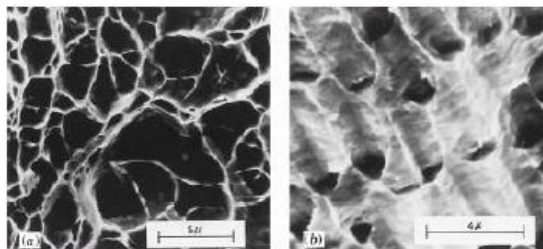


Figure 8.4 (a) Scanning electron fractograph showing spherical dimples characteristic of ductile fracture resulting from uniaxial tensile loads. 3300X. (b) Scanning electron fractograph showing parabolic-shaped dimples characteristic of ductile fracture resulting from shear loading. 5000X. (From R. W. Hertzberg, *Deformation and Fracture Mechanics of Engineering Materials*, 3rd edition. Copyright © 1989 by John Wiley & Sons, New York. Reprinted by permission of John Wiley & Sons Inc.)



Microscopic process of fracturing

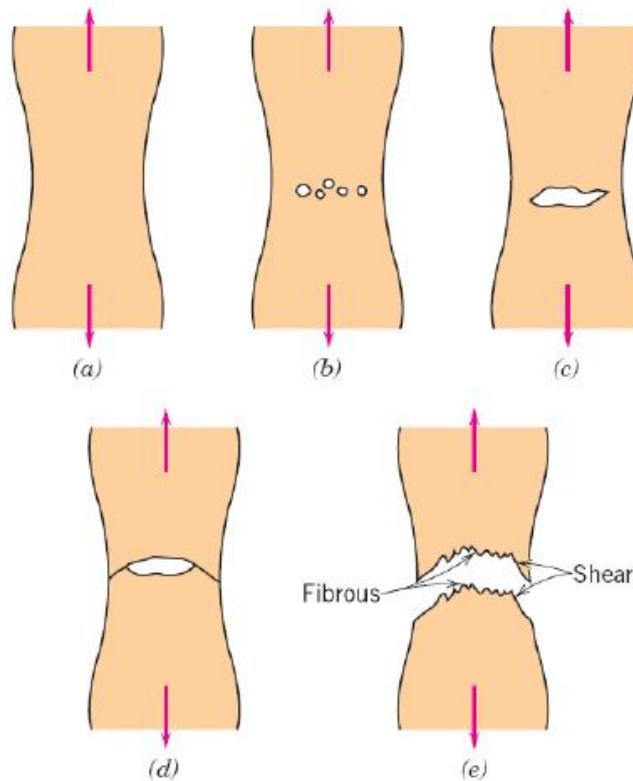
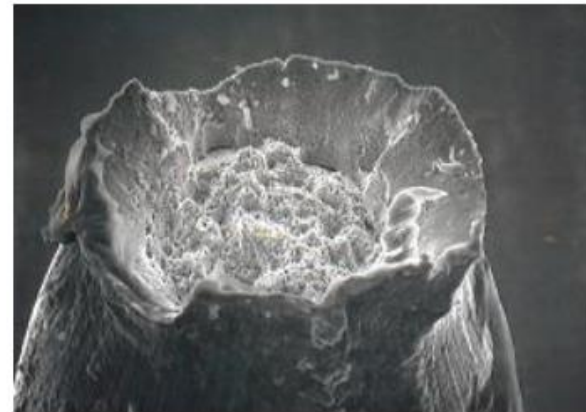


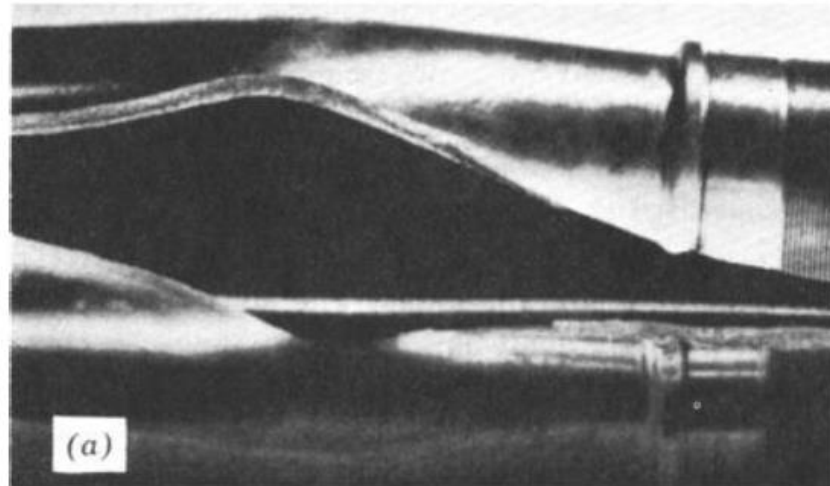
Figure 8.2 Stages in the cup-and-cone fracture. (a) Initial necking. (b) Small cavity formation. (c) Coalescence of cavities to form a crack. (d) Crack propagation. (e) Final shear fracture at a 45° angle relative to the tensile direction. (From K. M. Ralls, T. H. Courtney, and J. Wulff, *Introduction to Materials Science and Engineering*, p. 468. Copyright © 1976 by John Wiley & Sons, New York. Reprinted by permission of John Wiley & Sons, Inc.)



Fracture surface of tire cord wire loaded in tension. Courtesy of F. Roehrig, CC Technologies, Dublin, OH. Used with permission.

Examples of Ductile and Brittle Fracture of Pipes

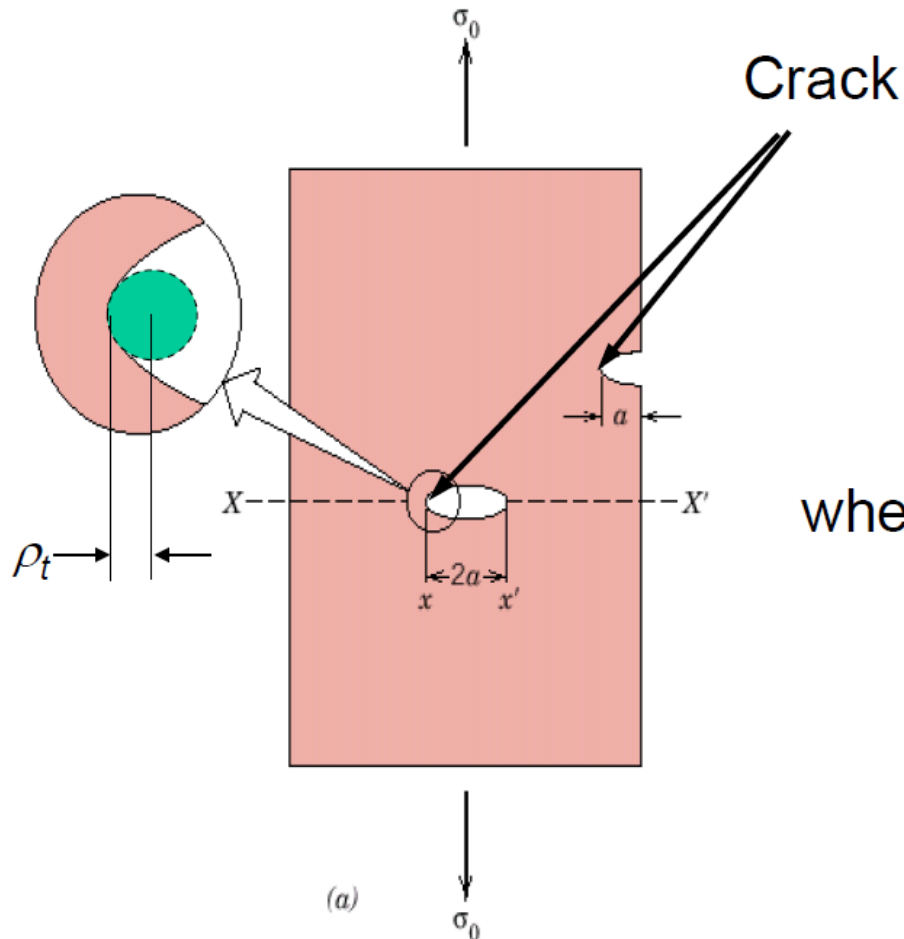
- **Ductile fracture:**
 - one piece
 - large deformation



- **Brittle fracture:**
 - many pieces
 - small deformations



Fracture Mechanics



$$\sigma_m = 2\sigma_o \left(\frac{a}{\rho_t} \right)^{1/2}$$

where

ρ_t = radius of curvature

σ_o = applied stress

σ_m = stress at crack tip

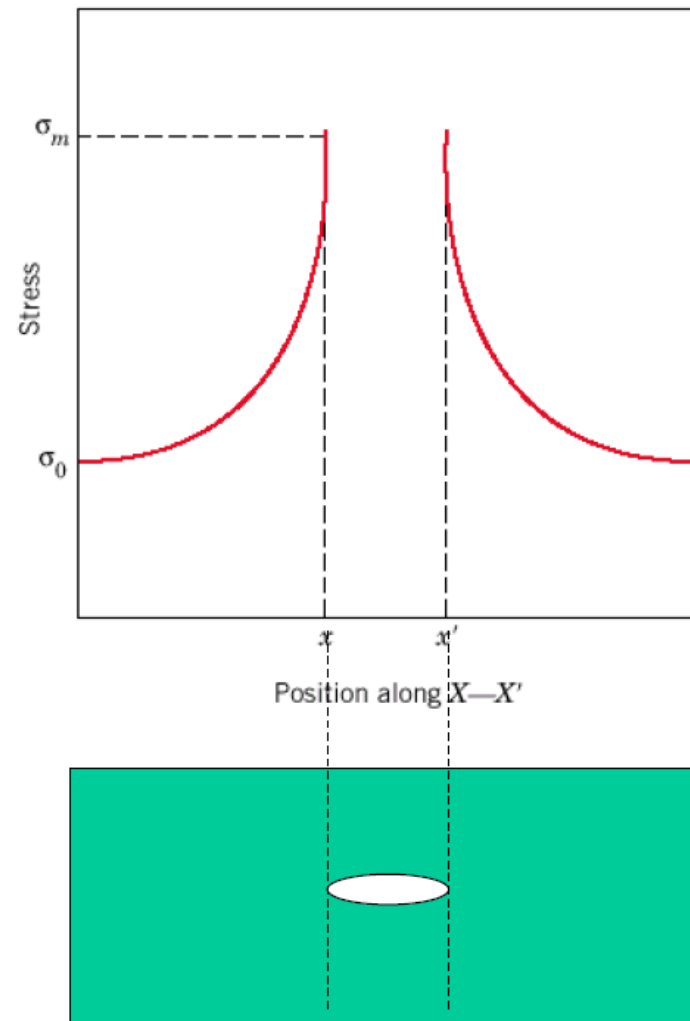


Fracture Mechanics

Stress Concentration at Crack Tip

K_t = stress concentration
factor

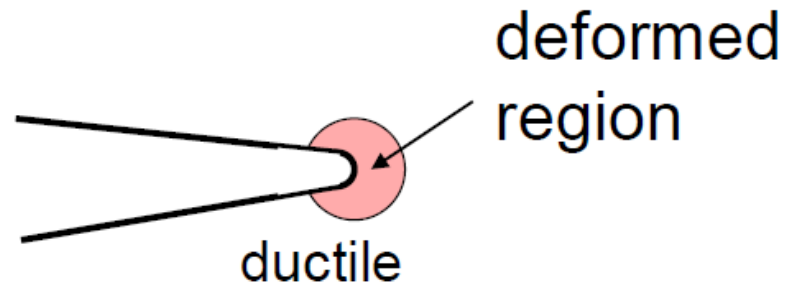
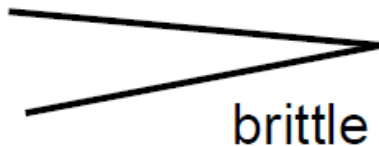
$$K_t = \frac{\sigma_m}{\sigma_o}$$





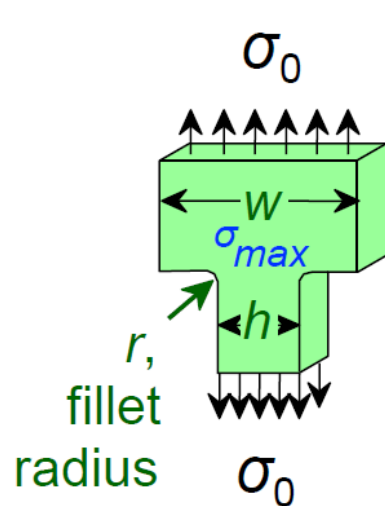
Crack Propagation

- Stress concentration higher for sharp cracks—propagate at lower stresses than cracks with blunt tips
- For ductile materials—plastic deformation at crack tip when stress reaches yield strength—tip blunted—lowers stress conc.

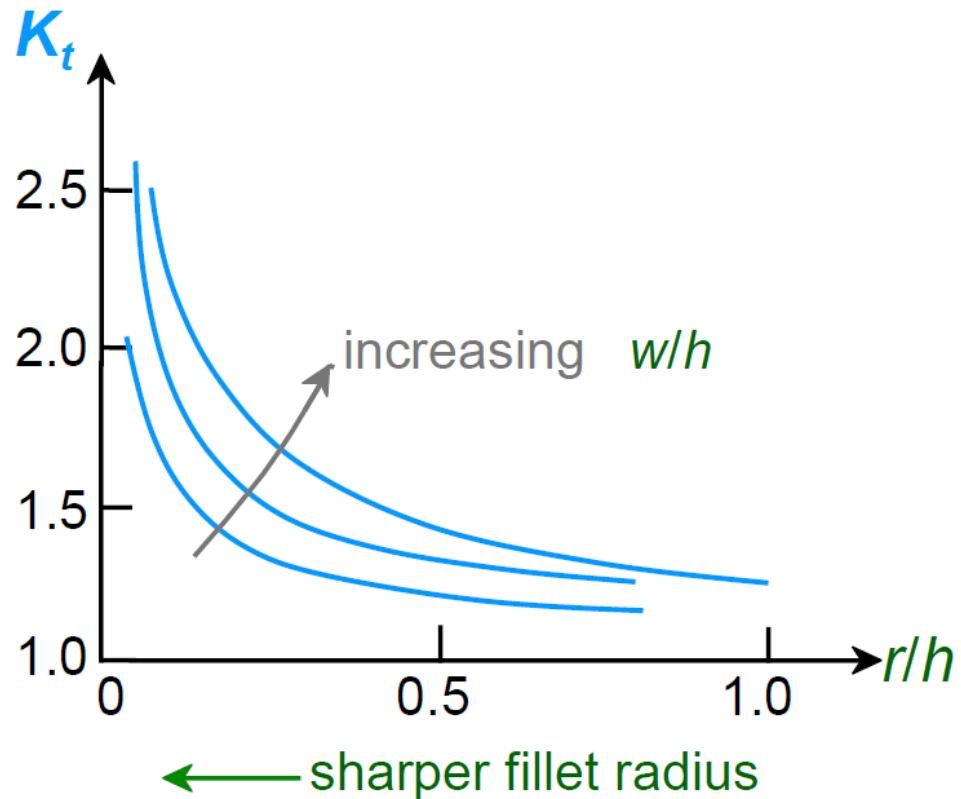


Crack Propagation

- **Avoid sharp corners!**

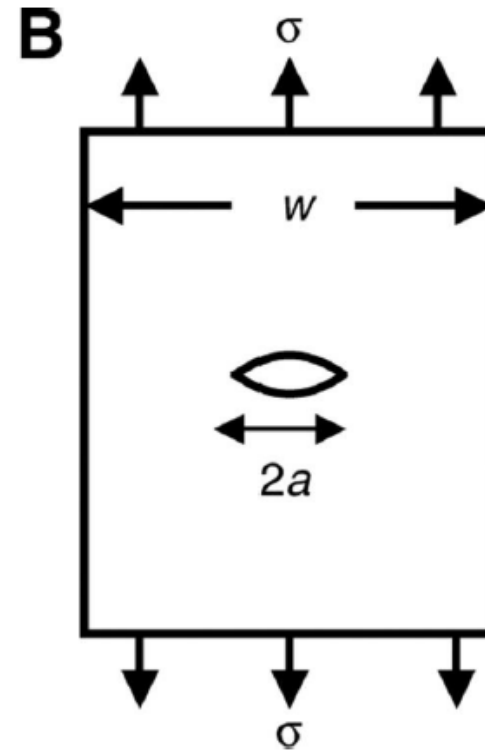
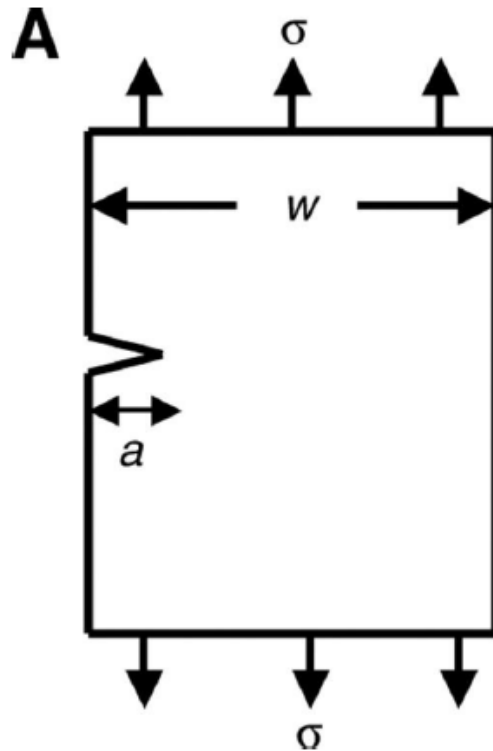


Adapted from Fig.
8.2W(c), *Callister 6e*.
(Fig. 8.2W(c) is from G.H.
Neugebauer, *Prod. Eng.* (NY),
Vol. 14, pp. 82-87 1943.)



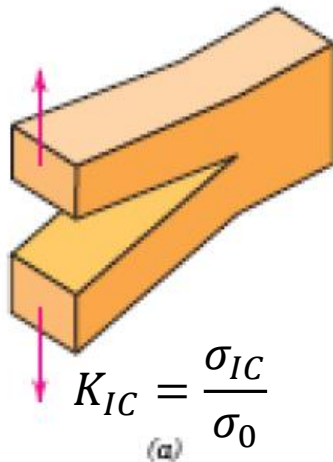


Fracture toughness

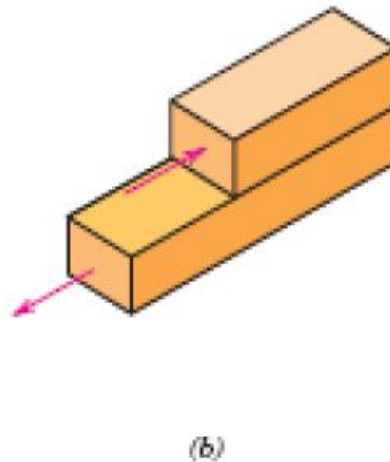




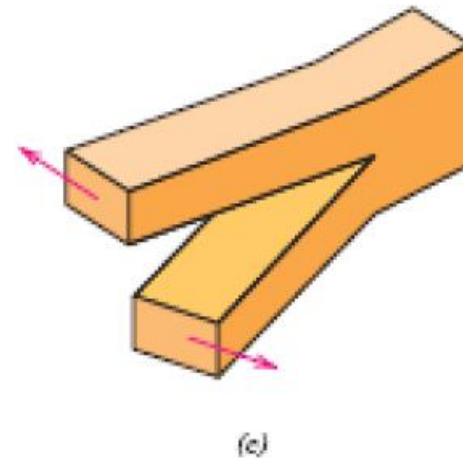
Fracture modes



Tensile mode



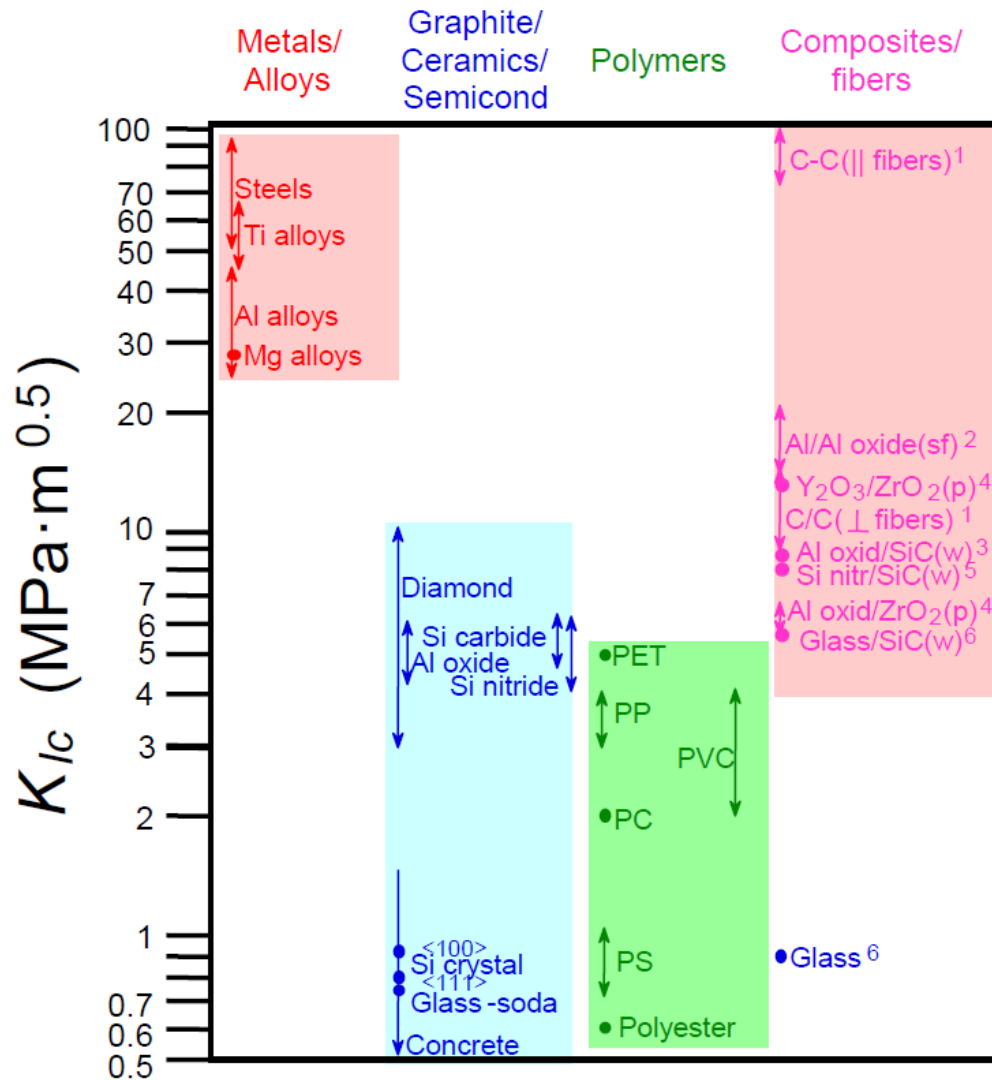
Sliding mode



Tearing mode



Fracture Toughness Ranges





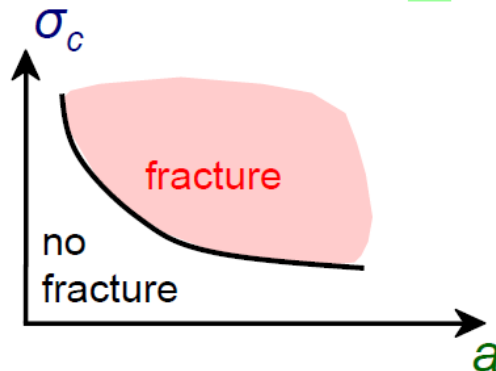
Design Against Fracture

- Crack growth condition:

$$K_{Ic} < Y\sigma_c\sqrt{\pi a}$$

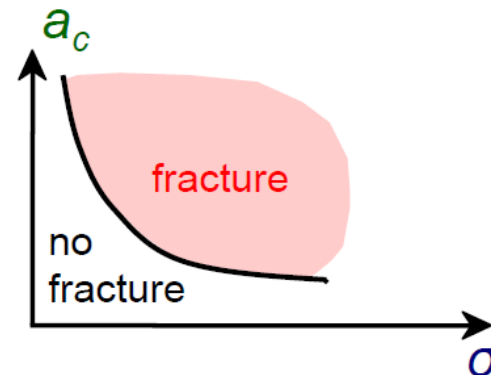
--Scenario 1: K_{Ic} and flaw size a specified - dictates max. design (critical) stress.

$$\sigma_c = \frac{K_{Ic}}{Y\sqrt{\pi a}}$$



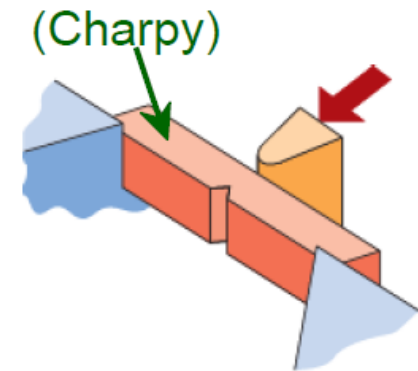
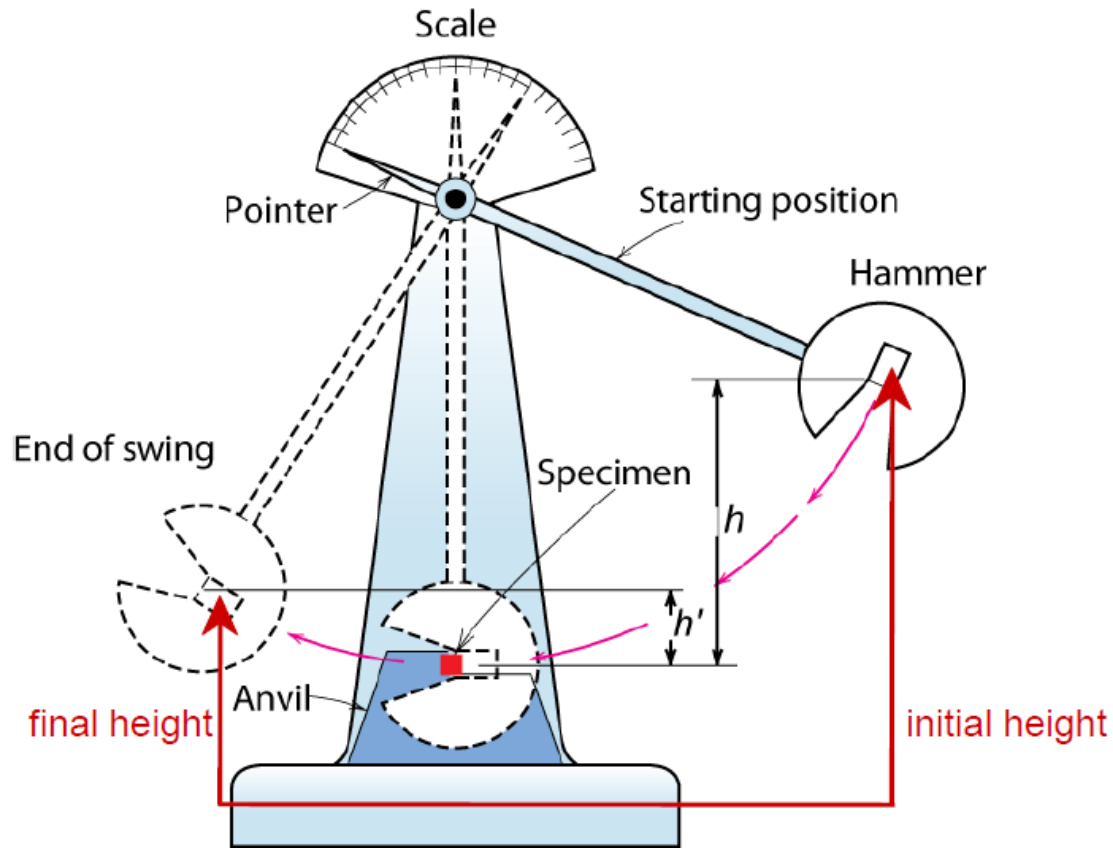
--Scenario 2: K_{Ic} and stress level specified - dictates max. allowable flaw size.

$$a_c = \frac{1}{\pi} \left(\frac{K_{Ic}}{Y\sigma} \right)^2$$





Impact fracturing test



Ductile-to-Brittle Transition

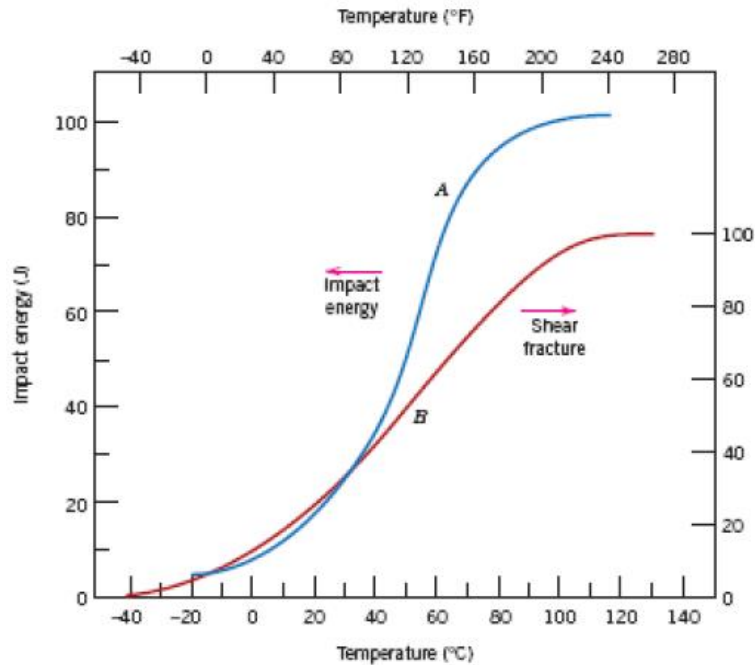
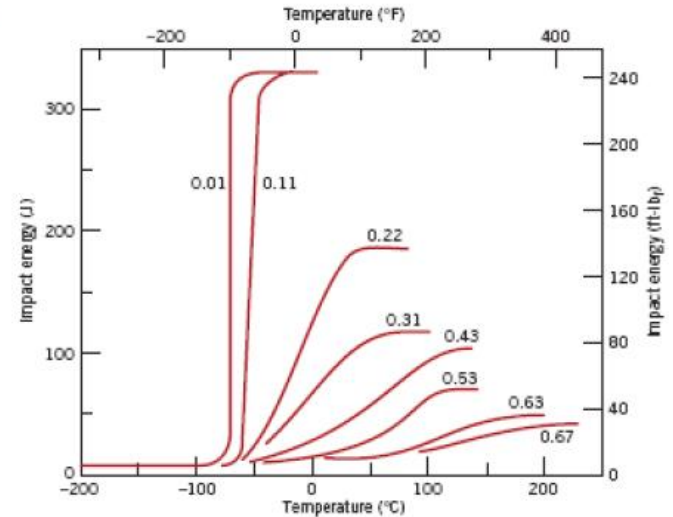


Figure 8.16
Influence of carbon content on the Charpy V-notch energy-versus-temperature behavior for steel. (Reprinted with permission from ASM International, Metals Park, OH 44073-9989, USA; J. A. Reinbolt and W. J. Harris, Jr., "Effect of Alloying Elements on Notch Toughness of Pearlitic Steels," *Transactions of ASM*, Vol. 43, 1951.)



Brittle Fracture

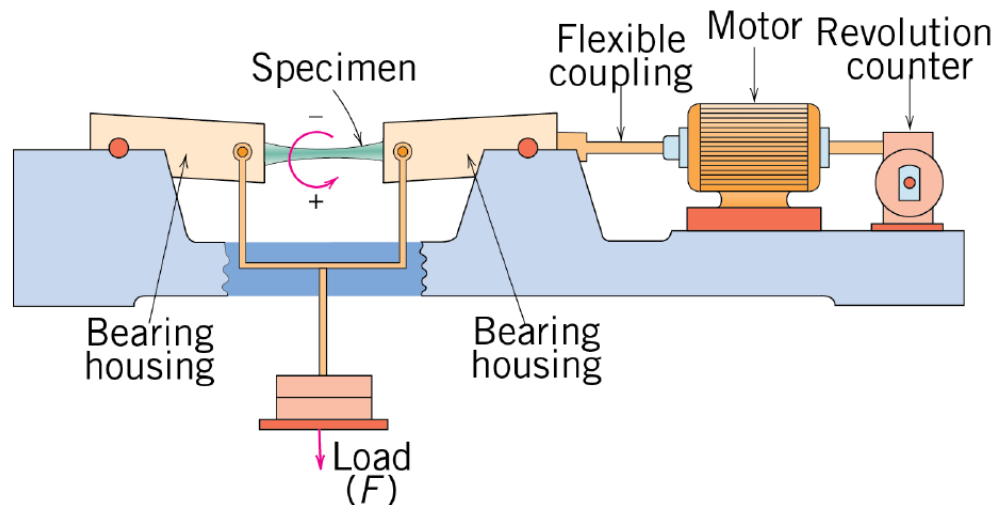
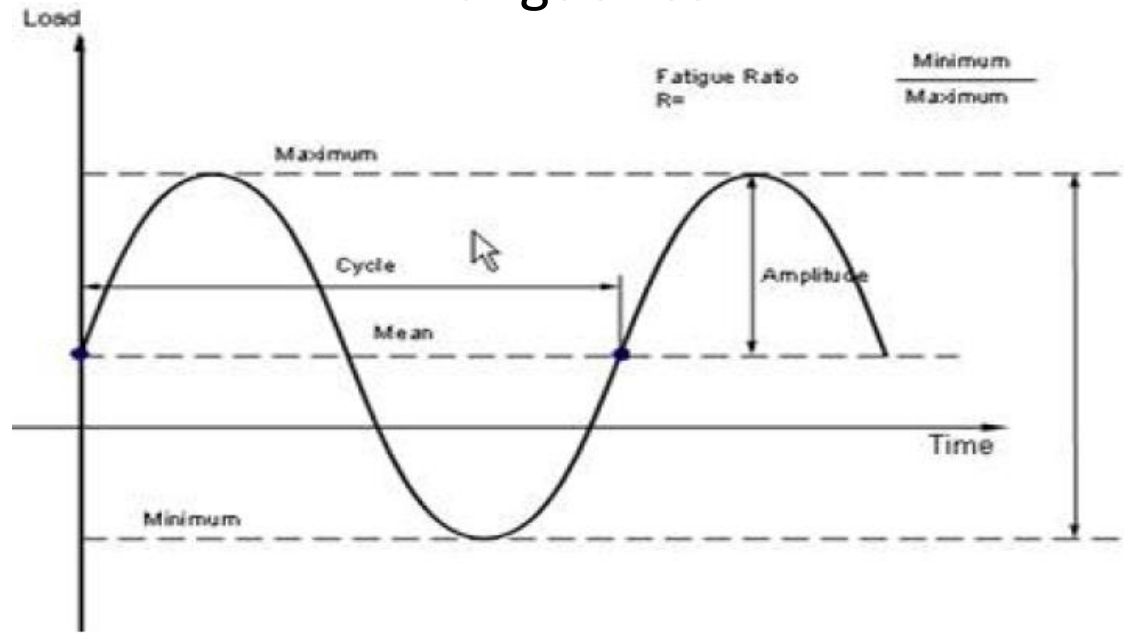


Ductile Fracture





Fatigue Test



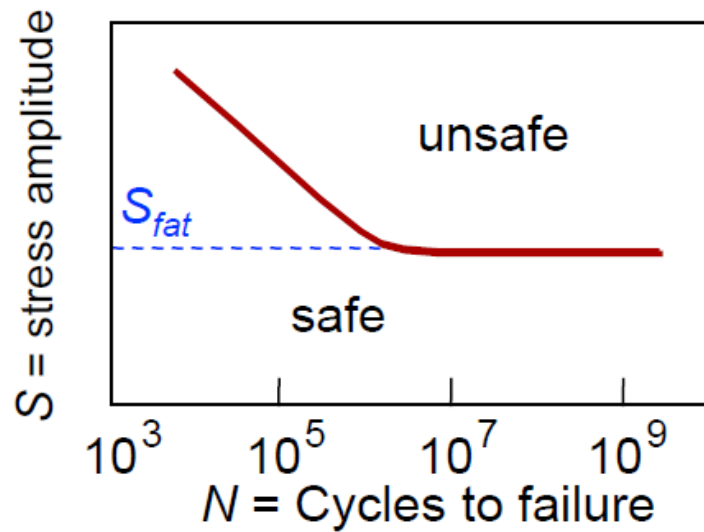


Fatigue Failure

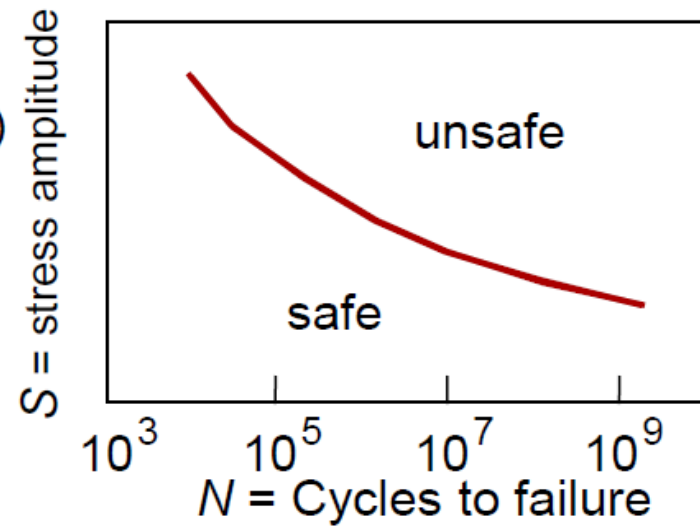




Types of Fatigue Behavior



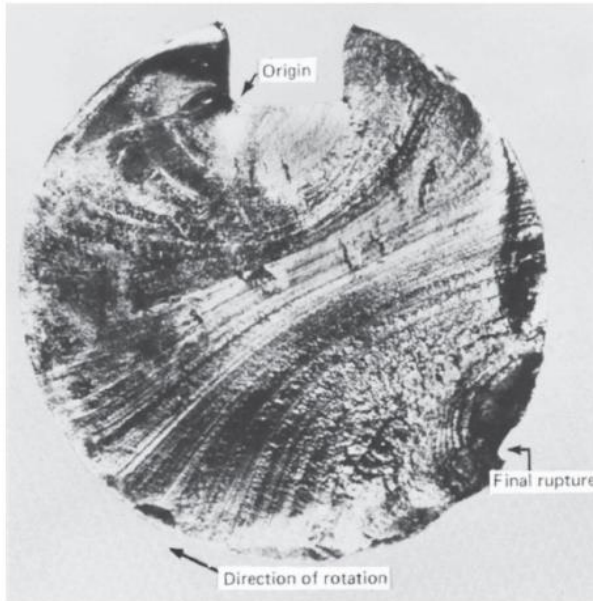
case for
steel (typ.)



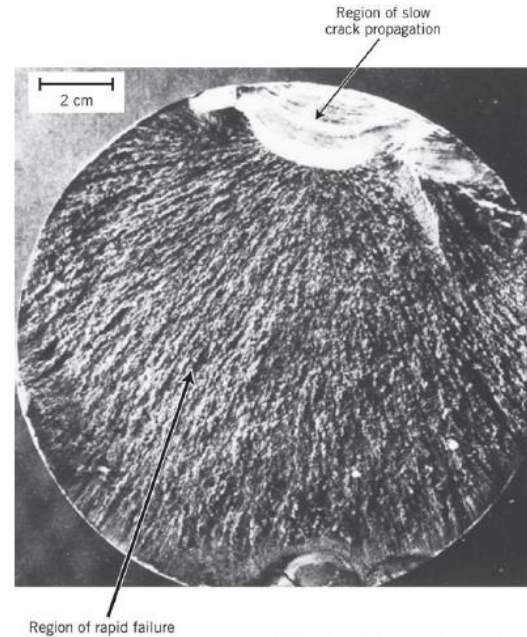
case for
Al (typ.)



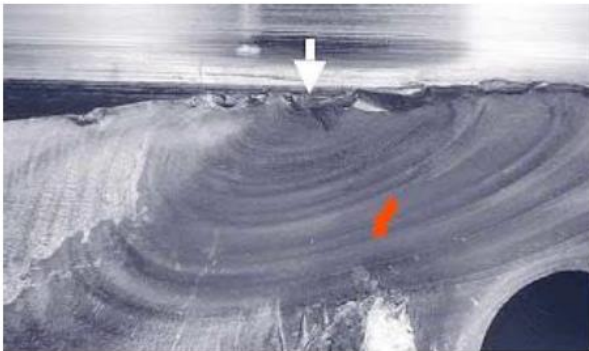
Types of Fatigue Behavior



Reproduced with permission from D. J. Wulpi, *Understanding How Components Fail*, American Society for Metals, Materials Park, OH, 1985.



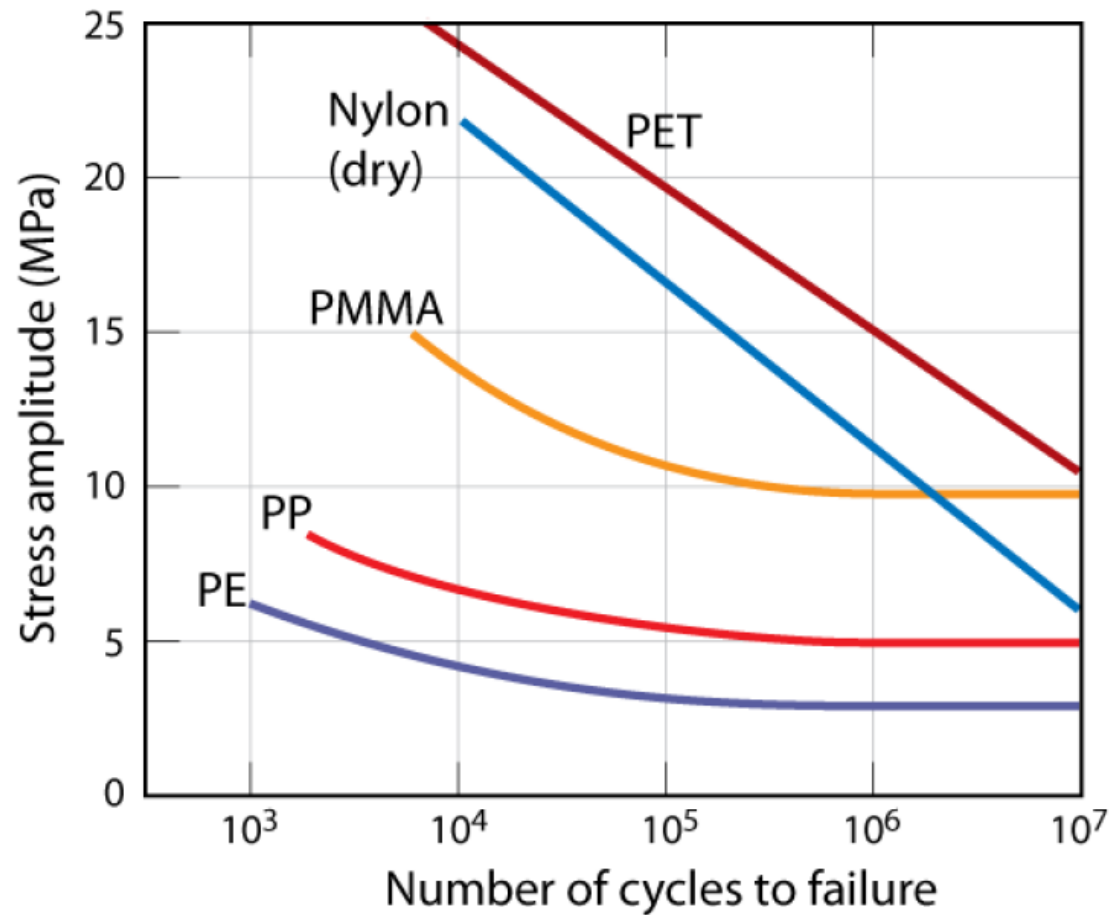
Reproduced by permission from *Metals Handbook: Fractography and Atlas of Fractographs*, Vol. 9, 8th edition, H. E. Boyer (Editor), American Society for Metals, 1974.





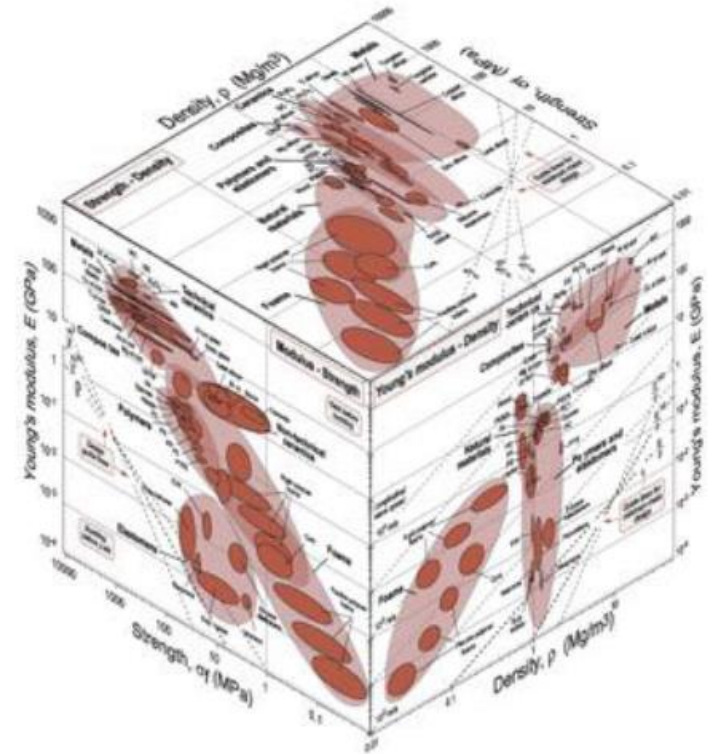
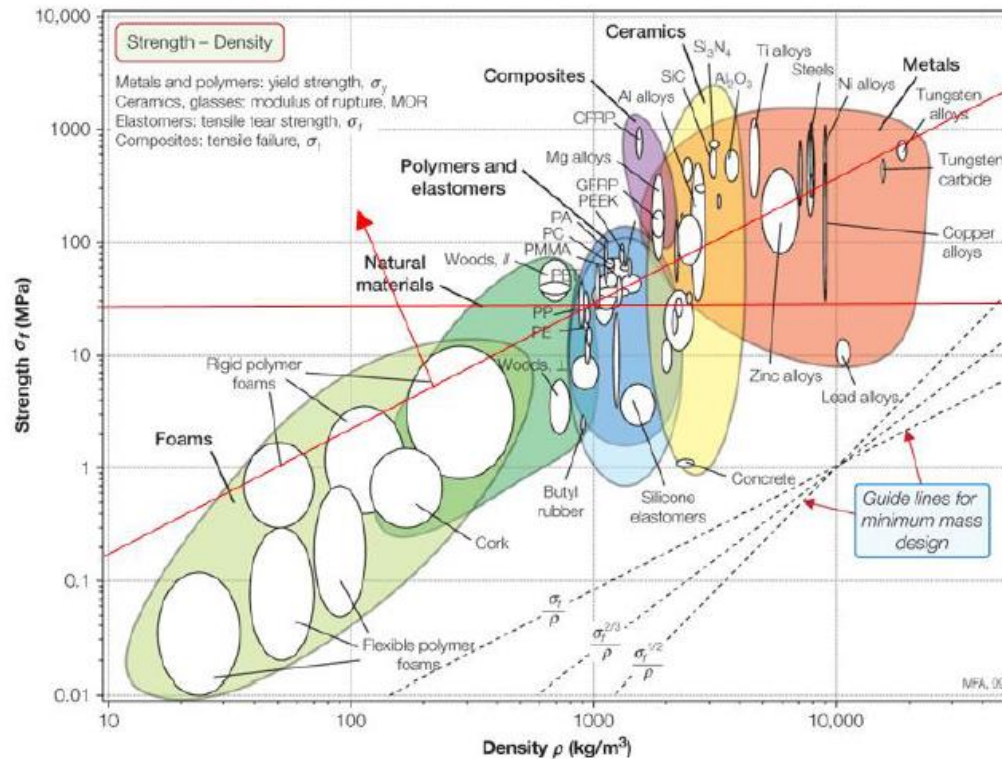
Fatigue Behavior of Polymers

- **Fatigue limit:**
 - PMMA, PP, PE
- **No fatigue limit:**
 - PET, Nylon (dry)





Ashby Chart





This Ashby plot shows the relationship between Young's modulus E (GPa) on the y-axis and density ρ (kg/m³) on the x-axis. The y-axis is logarithmic, ranging from 10^{-4} to 1000 . The x-axis is also logarithmic, ranging from 10 to $10,000$. The plot is divided into several material classes, each represented by a different color and containing representative materials:

- Technical ceramics:** Located in the top right, with high modulus and high density. Materials include Al_2O_3 , SiC, SiN, Ti alloys, Ni alloys, WC, W alloys, Cu alloy, and Lead alloys.
- Composites:** Located in the top center, with high modulus and moderate density. Materials include Glass, CFRP, GFRP, KFRP, PMMA, and Bamboo.
- Natural materials:** Located in the center, with moderate modulus and density. Materials include Wood, I grain, PMMA, PE, PS, Wood, I grain, PE, PE, PTFE, EVA, Cork, Isoprene, and Butyl rubber.
- Metals:** Located in the top right, with high modulus and high density. Materials include Ti alloys, Ni alloys, W alloys, Cu alloy, and Lead alloys.
- Nontechnical ceramics:** Located in the center right, with moderate modulus and high density. Materials include Concrete, PEEK, PEI, Epoxies, and PC.
- Polymers:** Located in the center, with moderate modulus and moderate density. Materials include PE, PTFE, EVA, Cork, Isoprene, and Butyl rubber.
- Foams:** Located in the bottom left, with low modulus and low density. Materials include Rigid polymer foams, Flexible polymer foams, and Cork.
- Elastomers:** Located in the bottom right, with low modulus and high density. Materials include Silicone elastomers, Polyurethane, Neoprene, and Butyl rubber.

Guide lines for minimum mass design are shown as dashed lines with slopes of $E^{1/3}/\rho$, $E^{1/2}/\rho$, and E/ρ . The plot also includes a box for 'Young's modulus - Density' and a box for 'Guide lines for minimum mass design'.

